Homework 5 (20 points each)

1. Obtain matix of rotation in 2 D space for rotation by angle ϕ

2. Generalize the matix of rotation in 3 D space expressed through unit vectors.

3. Show that matrix of rotation in 3 D space in the form of unit vectors is a orthogonal matirx i.e. $S^T = S^{-1}$

4. Obtain 3 D rotational matrix through the partial derivatives
like Eq.(3.33)
prove also the relation (3.34)

5. Calculate the gradient of f (r) r^n and consider cases of f = 1, n = 1, and f = 1 and n = -1.

6. Calculate divergence of f (r) $r^n \hat{r}$ as es of f = 1, n = 1, and f = 1 and n = -2.