## MET 3502/5561 Synoptic Meteorology Lecture 11: Curl, LaPlacian, Total Derivative, and Coordinate Systems

## 1. Vorticity/curl:

The cross product of  $\nabla$  with vector  $\vec{A}$  is called the curl of  $\vec{A}$ :

$$\nabla \times \vec{A} = \left(\frac{\partial}{\partial x}\vec{\iota} + \frac{\partial}{\partial y}\vec{j} + \frac{\partial}{\partial z}\vec{k}\right) \times \left(A_x\vec{\iota} + A_y\vec{j} + A_z\vec{k}\right)$$
$$= \begin{vmatrix} \vec{\iota} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix}$$



The curl of wind vector  $\vec{v}$  is called **vorticity**, which is a measure of the rotation of a fluid.

- 1) Vorticity represents rotation & distortion of an element of air when the wind increases cross stream.
- 2) A flow with zero curl is said to be irrotational. Positive vorticity is cyclonic (anticlockwise in Northern Hemisphere), negative vorticity is anticyclonic.



3) Convergence (divergence) tends to increase (decrease) the curl (vorticity).

## 2. Laplacian Operator:

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

Which is the gradient of gradient, or the rate change of gradient (second derivative)

Example: 
$$\nabla^2 T = \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2}$$

Physical Interpretation:

When there is A minimum in  $T \Longrightarrow \nabla^2 T > 0$ 

When there is A maximum in  $T \Longrightarrow \nabla^2 T < 0$ 

Maximum in *T* means there is minimum in  $\nabla^2 T$ 



3. Expansion of a total derivative (Martin's book, chapter 1.2.4):

D	$\partial$	
$\overline{Dt}$	$=\frac{1}{\partial t}$	+
-	Partial derivative	
Total Derivative	Euler rate of change	Negativ (remen
Lagrangian rate of change	Local rate of change	
Derivative following a parcel	Derivative at a point	

If steady state, then

 $\frac{\partial}{\partial t} = 0$ 

 $\frac{\partial T}{\partial t} = \frac{T_2 - T_1}{\Delta t}$ 

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ve Advection (remember advection is  $-\vec{v}\cdot\nabla$ )

(Rate of change following the flow)

•  $T_2$ 

at time 2

 $T_1 \bullet$ 

If everything is conserved,  $\frac{D}{Dt} = 0$ 

$$\frac{D}{Dt} = \frac{\partial}{\partial t} + u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}$$
  
For example:  $\frac{DT}{Dt} = \frac{\partial T}{\partial t} + \vec{v} \cdot \nabla T = \frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} + w \frac{\partial T}{\partial z}$ 

is frequently expressed in pressure coordinates:



If steady state at Miami, then  $\frac{\partial T}{\partial t} = 0$  (No local change, but we do have cold advection  $(\vec{v} \cdot \nabla T > 0)$  & surface heating  $(\frac{DT}{Dt} > 0)$  balance each other.)

$$\frac{DT}{Dt} = \frac{\partial T}{\partial t} + \vec{v} \cdot \nabla T$$

Advection:  $-\vec{v} \cdot \nabla$ , is based on the gradient of anything and wind direction.

Advection means how much the wind intersects the contour of any parameter; how much the wind wants to transfer.



If  $\nabla T \& \vec{v}$  are parallel, the advection is maximum

If  $\nabla T \& \vec{v}$  are perpendicular, the advection is 0.

## 4. Coordinate Systems:

- 1) Cartesian Coordinates: x, y, z (z along constant height surface, x to the east, y to the north)
- 2) Pressure Coordinates: x, y, P (P along constant pressure surface)

 $\frac{\partial}{\partial x_p}, \frac{\partial}{\partial y_p}$  — derivatives are taken along pressure surface, they are almost same as  $\frac{\partial}{\partial x'}, \frac{\partial}{\partial y'}$ , but for math convenience.

- 3) Isentropic Coordinates:  $x, y, \theta$  ( $\theta$  along potential temperature surface). Since  $\theta$  surfaces are of constant entropy, so ( $x, y, \theta$ ) are referred to as isentropic coordinates. This coordinate is usually for physical interpretation convenience.
- Autural Coordinates (Martin's book, chapter 4.4) (Wallace & Hobbs's book, chapter 8.1.3): defined following the flow/ fluid motion (streamlines)
   Advantage: can be useful for diagnosing force balance and the dynamics controlling parcel movement.



streamline (streamlines are arbitarily spaced lines parallel to  $\vec{v}$ )

Unit vectors

**Direction**: normal to the horizontal flow (perpendicular) **Magnitude**: distance directed normal to the streamline, toward the left of the streamline.

- Direction: tangential to the flow
- $\vec{s}$ : **Magnitude**: Arc length directed down stream.
- \* Unit vectors vary spatially (direction is changing).

So at any point in the flow,  $v \equiv |\vec{v}| = \frac{ds}{dt}$ , &  $\frac{dn}{dt} = 0$ .

Momentum Equation:  $\vec{(v = vs)}$ 

$$\frac{D\vec{v}}{Dt} = \frac{d(v\vec{s})}{dt} = \vec{s}\frac{dv}{dt} + v\frac{d\vec{s}}{dt} = \vec{s}\frac{dv}{dt} + \vec{n}\frac{v^2}{R}$$
(R is radius of carvature  
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