

This is an outline of some topics from my final Linear Algebra lectures from various years, 2004 to 2011. Some are not in our textbook. Most semesters I don't have time for many of these. You won't be tested on those I didn't cover in class.

1) MATLAB does not compute eigenvalues of A from $p(\lambda)$ like we do. One reason is that it is generally impossible to factor (exactly) a polynomial of degree 5 or higher. Instead:

a) Note that if T is triangular then its eigenvalues are its diagonal entries. Easy!

b) If A is similar to T (see Schur's Theorem) then they have the same eigenvalues, so we'd like to find such a T .

c) We use the GS process to factor $A = QR$, where R is triangular. We set $A_2 = RQ$, which is similar to A , and factor it as Q_2R_2 . We repeat indefinitely, setting $A_3 = R_2Q_2 = Q_3R_3$ etc. We get a sequence of similar matrices, and can expect (reasoning omitted) that they become "more and more triangular" and pretty close to T . So, we can take the diagonal entries of one of them (say A_1) to be pretty close to the eigenvalues we want.

2) A few simple exercises for practice:

a) If A has n LI eigenvectors then so do A^T and A^{-1} (if it exists). [the easy proofs are based on the diagonalization of A and facts about similarity from Ch.4.3]

b) If A is 3×3 , with only 2 eigenvalues, and each eigenspace has $\dim = 1$, then is A diagonalizable? Ans: No, it only has 2 LI eigenvectors.

3) *The Spectral Decomposition* of A is the formula in exercise 6.4.22 of the 7th Ed. Be able to justify it by multiplying out the formula $A = UDU^H$. Notice that $u_1u_1^H$, for example, is an $n \times n$ matrix that projects vectors onto $\text{span}\{u_1\}$. So, Ax can be thought of as a linear combination of projections onto eigenvectors.

4) Omitted, but not hard - The very short proof of Cor 6.4.5, and of its converse: If A is real and has a complete orthogonal set of e'vecs [so $A = UDU^T$], then A is symmetric. (try this yourself).

5) Approximation by trig polynomials (see Ch 5.5 and exercises 5.5.28 to 30). the answer was $\pi/2 - 4\cos(x)/\pi$.) Here is a similar problem, from a previous semester.

Find the n^{th} Fourier approximation to $f(t) = t$ on $[0, 2\pi]$.

Solution: The problem asks us to find the projection of the vector $f(t) = t$ onto the span of the vectors (the trig functions) listed on page 280. The formula for the projection $t_n(x)$ is at the top of page 282, and is really the same as the formula in Thm 5.5.7 (the c_i of 5.5.7 are the a_k and b_k of pages 280-282). From integration by parts,

$$b_k = \langle t, \sin(kt) \rangle = \frac{1}{\pi} \int_0^{2\pi} t \sin(kt) dt = -k/t$$

and similarly, we get $a_k = 0$ except that $a_0 = \pi/\sqrt{2}$. So the answer is,

$$t_n(x) = \pi + (-2) \sin(t) + (-2/2) \sin(2t) + (-2/3) \sin(3t) + \dots + (-2/n) \sin(nt)$$

This is a good approximation to f if n is big (and x is not too close to the endpoints of $[0, 2\pi]$). It is like a Taylor polynomial, and is useful in differential equations (etc). The infinite series version is called the Fourier series of $f(t) = t$.

6) A good example to know about is the *nilpotent* matrix below. Check that $A^3 = O$. It has a repeated eigenvalue of 0, and is defective. (see also HW 6.1.7).

$$A = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

7) In Spring 2011, we went over the Google application in Ch 6.3 (pg 333).