

Answer all 6 questions. An unjustified answer will receive little or no credit. No calculators or formula sheets are allowed.

- (15) 1. Find the solution of each of the following ODE
- (a) $y'' - 6y' + 9y = 0$ with $y(0) = 1$ & $y'(0) = 5$
- (b) $y'' + 4y = 0$ with $y(0) = 3$ & $y'(0) = -8$.
- (20) 2. Find the general solution of each of the following ODEs
- (a) $y''' - 3y' + 2y = 4x^2$ (b) $y'' + 2y' - 3y = 12e^x$.
- (20) 3. Find y_c and give the minimal form of the y_p that one should try for each of the following ODE
- (a) $(D^2 + 2D + 5)^2 y = 3x e^{-x} \sin(2x)$
- (b) $(D^2 + 1)^2 (D - 2)^3 y = 6 \cos^2 x + 2 \cos x$
- (15) 4(a) Define what it means for $\{f_1, \dots, f_n\}$ to be linearly dependent.
- (b) Given that $f(x) = x$ is a solution of $(x^2 + 1)y'' - 4xy' + 4y = 0$, find a second linearly independent solution.
- (15) 5(a) Write down what Hooke's law says.
- (b) Find a particular solution of the ODE $y'' + y = \sec^2 x$.
- (15) 6. A body of mass 4 kg is attached to a Hooke-type spring with spring constant $k = 20 \text{ Nm}^{-1}$ on a horizontal frictionless surface. The air resistance to the motion is also λv where $\lambda = 16 \text{ Nsm}^{-1}$. If the spring is extended by an amount of 3m at time $t = 0$ and then let loose, find the position of the body at all subsequent times.

1(a) $y'' - 6y' + 9y = 0 \quad \therefore (D^2 - 6D + 9)y = 0$
 $\therefore (D-3)^2 y = 0 \Rightarrow (D-3)^2 = 0 \Rightarrow D = 3$ (twice)
 $\therefore y = (C_1 + C_2 x)e^{3x}$ is the general solution.
 $\therefore y' = [C_2 + 3(C_1 + C_2 x)]e^{3x}$
 $y(0) = 1 \Rightarrow C_1 + C_2 \cdot 0 = 1$
 $y'(0) = 5 \Rightarrow C_2 + 3(C_1 + C_2 \cdot 0) = 5$
 $\therefore C_1 = 0 \quad \text{So } C_2 = 5 - 3C_1 = 5$
 $\therefore y = (1 + 2x)e^{3x}$

(b) $y'' + 4y = 0 \quad \therefore (D^2 + 4)y = 0 \Rightarrow D = \pm 2i$
 $\therefore y = C_1 \cos(2x) + C_2 \sin(2x)$ is the general solution
 $\therefore y = -2C_1 \sin(2x) + 2C_2 \cos(2x)$
 $y(0) = 3 \Rightarrow C_1 \cdot 1 + C_2 \cdot 0 = 3 \Rightarrow C_1 = 3$
 $y'(0) = -8 \Rightarrow -2C_1 \cdot 0 + 2C_2 \cdot 1 = -8 \Rightarrow C_2 = -4$
 $\therefore y = 3 \cos(2x) - 4 \sin(2x)$

2(a) $y'' - 3y' + 2y = 0 \Rightarrow (D^2 - 3D + 2)y = 0$
 $\therefore (D-1)(D-2)y = 0 \Rightarrow y_c = C_1 e^x + C_2 e^{2x}$
 Try $y_p = Ax^2 + Bx + C$. Then $y_p' = 2Ax + B$
 and $y_p'' = 2A$. So $y_p'' - 3y_p' + 2y_p = 4x^2$ becomes
 $2A - 3(2Ax + B) + 2(Ax^2 + Bx + C) = 4x^2$
 $\therefore 2A = 4 \quad (\text{coeff. of } x^2) \Rightarrow A = 2$
 $-6A + 2B = 0 \quad (\text{coeff. of } x) \Rightarrow B = 6$
 $2A - 3B + 2C = 0 \quad (\text{coeff. of } x^0) \Rightarrow C = 7$
 $\therefore y_p = 2x^2 + 6x + 7$. Hence $y = y_c + y_p$
 $= C_1 e^x + C_2 e^{2x} + 2x^2 + 6x + 7$

$$2(b) \quad y'' + 2y' - 3y = 0 \Rightarrow (D^2 + 2D - 3)y = 0$$

$$\Rightarrow (D-1)(D+3)y = 0 \Rightarrow y_c = C_1 e^x + C_2 e^{-3x}$$

Try $y_p = Ax e^x$ (because 1 is a root of mult. 1)

$$\text{Then } y_p' = (Ax+A)e^x \text{ and } y_p'' = (Ax+2A)e^x.$$

So $y_p'' + 2y_p' - 3y_p = 12e^x$ becomes

$$[(Ax+2A) + 2(Ax+A) - 3(Ax)]e^x = 12e^x$$

$$\therefore 4A e^x = 12e^x \Rightarrow A = 3. \text{ So } y_p = 3xe^x$$

$$\therefore y = y_c + y_p = C_1 e^x + C_2 e^{-3x} + 3xe^x.$$

$$3(a) \quad (D^2 + 2D + 5)^2 y = 0 \Rightarrow D = (-2 \pm \sqrt{4-20})/2 = -1 \pm 2i \text{ (twice)}$$

$$\therefore y_c = e^{-x} [(C_1 + C_2 x) \cos(2x) + (C_3 + C_4 x) \sin(2x)]$$

The minimal form of y_p that one should try is

$$y_p = e^{-x} \cdot x^2 [(A_0 + A_1 x) \cos(2x) + (B_0 + B_1 x) \sin(2x)]$$

because $3x$ is a polynomial of degree 1 and $-1 \pm 2i$ is a root of multiplicity 2.

$$(b) \quad (D^2 + 1)^2 (D-2)^3 y = 0 \Rightarrow D = 2 \text{ (3 times) or } D = \pm i \text{ (twice)}$$

$$\therefore y_c = (C_1 + C_2 x + C_3 x^2) e^{2x} + (C_4 + C_5 x) \cos x + (C_6 + C_7 x) \sin x$$

Now observe that $6 \cos^2 x = 6 \cdot \frac{1}{2} [1 + \cos(2x)] = 3 + 3 \cos(2x)$

$$\text{So } (D^2 + 1)^2 (D-2)^3 y = 6 \cos^2 x + 2 \cos x$$

$$= 3 + 3 \cos(2x) + 2 \cos x$$

Since $\pm i$ is a root of multiplicity 2 we should

try $(A_0 \cos x + B_0 \sin x) \cdot x^2$ as a part of y_p

to cater for the " $2 \cos x$ ". Also since 3 and

$3 \cos(2x)$ are not involved in y_c , we should add

$A_1 \cos(2x) + B_1 \sin(2x) + A_2$ to our y_p to cater

for the " $3 \cos(2x)$ " and the " 3 ". Hence the minimal form of the y_p that one should try is

$$y_p = (A_0 \cos x + B_0 \sin x) \cdot x^2 + A_1 \cos(2x) + B_1 \sin(2x) + A_2.$$

4(a) The functions f_1, \dots, f_n are linearly dependent if we can find constants c_1, \dots, c_n which are not all zero such that $c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) \equiv 0$.

(b) A second linearly indep. solution is given by $y_2 = v \cdot f(x)$ where

$$v = \int \frac{e^{-\int [a_1(x)/a_0(x)] dx}}{[f(x)]^2} dx = \int \frac{e^{-\int \frac{-4x}{x^2+1} dx}}{[x]^2} dx$$

$$= \int \frac{e^{2 \ln(x^2+1)}}{x^2} dx = \int \frac{e^{\ln(x^2+1)^2}}{x^2} dx = \int \frac{(x^2+1)^2}{x^2} dx$$

$$= \int \frac{x^4 + 2x^2 + 1}{x^2} dx = \int (x^2 + 2 + x^{-2}) dx = \frac{x^3}{3} + 2x - x^{-1}$$

$$\therefore y_2(x) = v \cdot f(x) = x \left[\frac{x^3}{3} + 2x - x^{-1} \right] = \frac{1}{3} x^4 + 2x^2 - 1.$$

5(a) Hooke's Law: The force with which a Hooke-type spring pulls back is directly proportional to the amount it is extended from its natural length.

(b) We know one $y_p = v_1 y_1 + v_2 y_2$ where y_1 & y_2 are two linearly indep. solutions of the homog. equation and $v_1' = \begin{vmatrix} 0 & y_2 \\ F(x) & y_2' \end{vmatrix} / \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$ & $v_2' = \begin{vmatrix} y_1 & 0 \\ y_1' & F(x) \end{vmatrix} / \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$

Homog. Eq. is $y'' + y = 0$. So take $y_1 = \cos x$ & $y_2 = \sin x$

$$\therefore v_1' = \begin{vmatrix} 0 & \sin x \\ \sec^2 x & \cos x \end{vmatrix} / \begin{vmatrix} \cos x & \sin x \\ -\sin x & \cos x \end{vmatrix} = \frac{-\sin x \cdot \sec^2 x}{\cos^2 x + \sin^2 x}$$

$$= -\frac{\sin x}{\cos x} \cdot \sec x = -\tan x \cdot \sec x$$

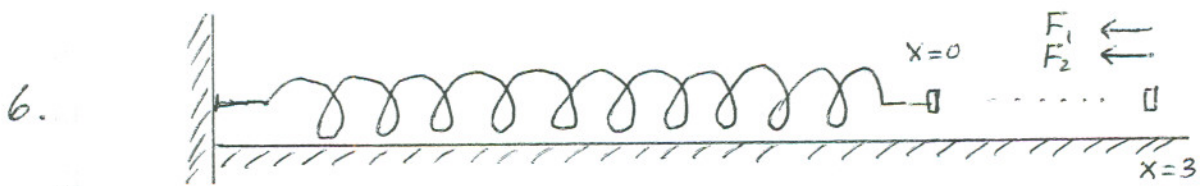
$$\therefore v_1 = \int -\tan x \sec x = -\sec x = -1/\cos x.$$

$$\text{Also } v_2' = \begin{vmatrix} \cos x & 0 \\ -\sin x & \sec^2 x \end{vmatrix} / \begin{vmatrix} \cos x & \sin x \\ -\sin x & \cos x \end{vmatrix} = \frac{\cos x \cdot \sec^2 x}{\cos^2 x + \sin^2 x}$$

$$= \frac{1}{\sec x} \cdot \sec^2 x = \sec x. \quad \therefore v_2 = \int \sec x dx$$

$$= \ln(\sec x + \tan x)$$

$$\therefore y_p = \cos x \cdot \frac{-1}{\cos x} + \sin x \cdot \ln(\sec x + \tan x) = -1 + \sin x \ln(\sec x + \tan x).$$



$$m\ddot{x} = -F_1 - F_2 = -\lambda v - kx$$

$$\therefore m\ddot{x} + \lambda\dot{x} + kx = 0$$

$$\therefore 4\ddot{x} + 16\dot{x} + 20x = 0 \Rightarrow \ddot{x} + 4\dot{x} + 5x = 0$$

$$\therefore D^2 + 4D + 5 = 0 \Rightarrow D = \frac{-4 \pm \sqrt{16 - 20}}{2} = -2 \pm i$$

$$\text{So } x(t) = e^{-2t}(A \cos t + B \sin t)$$

$$\begin{aligned} \therefore \dot{x}(t) &= -2e^{-2t}(A \cos t + B \sin t) + e^{-2t}(-A \sin t + B \cos t) \\ &= e^{-2t}[(B - 2A) \cos t - (2A + B) \sin t] \end{aligned}$$

$$x(0) = 3 \Rightarrow A \cdot 1 + B \cdot 0 = 3 \Rightarrow A = 3$$

$$\dot{x}(0) = 0 \Rightarrow (B - 2A) \cdot 1 - (2A + B) \cdot 0 = 0 \Rightarrow B = 6$$

$$\therefore x(t) = 3e^{-2t}(\cos t + 2 \sin t) \quad \text{END}$$

The question did not ask for a sketch of $x(t)$ but if it did, this is how you would do that.

$$\begin{aligned} x(t) &= 3e^{-2t} \cdot \sqrt{5} \left[\cos t \cdot \frac{1}{\sqrt{5}} + \sin t \cdot \frac{2}{\sqrt{5}} \right] \\ &= 3\sqrt{5} e^{-2t} (\cos t \cos \alpha + \sin t \sin \alpha) \\ &= 3\sqrt{5} e^{-2t} \cos(t - \alpha) \quad \text{where } \tan \alpha = \frac{2}{1} = 2. \end{aligned}$$

