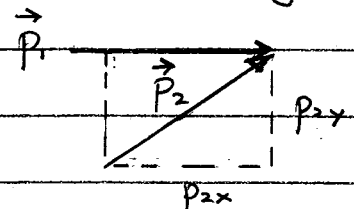
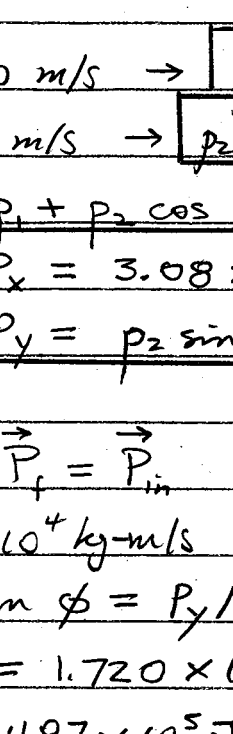


① a)  $M_1 = 1500 \text{ kg}, V_1 = 12.0 \text{ m/s} \rightarrow p_1 = M_1 V_1 = 1.80 \times 10^4 \text{ kg-m/s}$   
 $M_2 = 2000 \text{ kg}, V_2 = 8.0 \text{ m/s} \rightarrow p_2 = M_2 V_2 = 1.60 \times 10^4 \text{ kg-m/s}$

b)   $P_x = p_1 + p_2 \cos 36.9$   
 $\rightarrow P_x = 3.08 \times 10^4 \text{ kg-m/s}$   
 $P_y = p_2 \sin 36.9 = 9.61 \times 10^3 \text{ kg-m/s}$

c) Momentum conserv.  $\Rightarrow \vec{P}_f = \vec{P}_{in}$   
 $P_{in} = \sqrt{P_x^2 + P_y^2} = 3.220 \times 10^4 \text{ kg-m/s} \Rightarrow V_f = P_{in} / (M_1 + M_2)$   
 $\rightarrow V_f = 9.22 \text{ m/s} \quad \tan \phi = P_y / P_x = 0.3120 \rightarrow \phi = 17.3^\circ$

d)  $K_{in} = \frac{1}{2} M_1 V_1^2 + \frac{1}{2} M_2 V_2^2 = 1.720 \times 10^5 \text{ J}$   
 $K_{fin} = \frac{1}{2} (M_1 + M_2) V_f^2 = 1.487 \times 10^5 \text{ J}$   
 $\Rightarrow K_{lost} = K_{in} - K_f = 2.33 \times 10^4 \text{ J}$

② a)  block:  $ma = F_T - F_g = mg - F_T$  (1)  
disk:  $I\alpha = F_T R \Rightarrow F_T = I\alpha / R$  (2)  
 no slipping condition  $\rightarrow \alpha = a/R$  (3)  
 Substitute Eqs (2) and (3) into Eq (1)

$\rightarrow ma = mg - I\alpha / R^2 \Rightarrow a = mg / (m + I/R^2)$

$I = 0.12 \text{ kg-m}^2, m = 0.35 \text{ kg}, R = 0.25 \text{ m} \rightarrow a = 1.51 \text{ m/s}^2$

b) 5 revs  $\rightarrow \Delta\theta = 5 \times 2\pi = 10\pi$  radians,  $\alpha = a/R = 6.044 \text{ rad/s}^2$   
 $\Delta\theta = \frac{1}{2} \alpha t^2 \Rightarrow t = \sqrt{2(\Delta\theta) / \alpha} \rightarrow t = 3.22 \text{ sec}$

c) Energy conserv  $\Rightarrow K_{tot} = mgh = mg[5(2\pi R)] = (10\pi)mgR$   
 $\rightarrow K_{tot} = 26.9 \text{ J}$

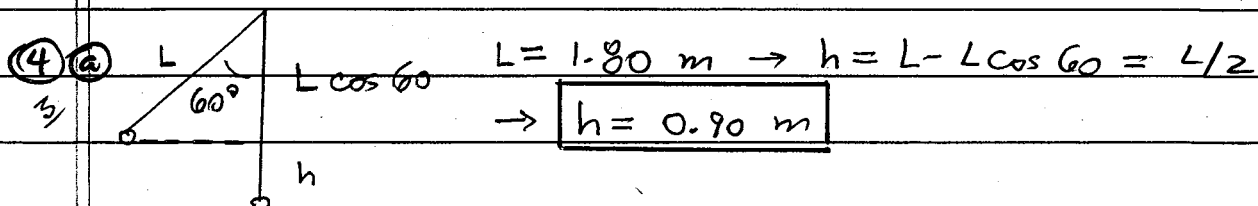
d)  $K_{trans} = \frac{1}{2} mV^2$  and  $K_{rot} = \frac{1}{2} I\omega^2 = \frac{1}{2} I V^2 / R^2 = \frac{1}{2} (I/R^2) V^2$   
 $\rightarrow \frac{K_{trans}}{K_{tot}} = \frac{m}{m + I/R^2} = 0.15 \quad \frac{K_{rot}}{K_{tot}} = \frac{I/R^2}{m + I/R^2} = 0.85$

3) a)  $m = 0.120 \text{ kg}, r = 0.200 \text{ m}, v = 4.0 \text{ m/s}$   
 $\Rightarrow L_m = mvr = 0.096 \text{ kg-m}^2/\text{s}$

b) Ang. mom. conserv  $\Rightarrow L_d + L_m = 0 \Rightarrow I\omega = -L_m$   
 $I = 0.150 \text{ kg-m}^2 \Rightarrow \omega = -L_m/I = -0.64 \text{ rad/s}$   
 $\rightarrow$  rotates opposite way mouse runs

c)  $K_{\text{total}} = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2 = 0.96 \text{ J} + 0.031 \rightarrow K_{\text{tot}} = 0.99 \text{ J}$

d) 3 revs  $\rightarrow \Delta\theta = 3(2\pi) = 6\pi \text{ rads} \rightarrow \Delta\theta = |\omega|t$   
 $\Rightarrow t = (\Delta\theta)/|\omega| = 29.5 \text{ sec}$



b)  $E_{\text{bottom}} = E_{\text{top}} \Rightarrow \frac{1}{2}m_B v^2 = m_B gh \Rightarrow v = \sqrt{2gh}$   
 $\Rightarrow v = 4.20 \text{ m/s}$

c) momentum conserv  $\rightarrow m_A v_B + m_B v_B = m_B v$  (1)  
 elastic collision  $\rightarrow v_B - v_A = -v$  (2)

Eq(1) +  $m_A \times$  Eq(2)  $\rightarrow (m_A + m_B)v_B = (m_B - m_A)v$

$m_A = 0.90 \text{ kg}, m_B = 1.50 \text{ kg} \Rightarrow v_B = 0.25 v = 1.05 \text{ m/s}$

$\rightarrow v_A = v + v_B = 5.25 \text{ m/s}$

d) Energy conserv  $\rightarrow m_A gh_A = \frac{1}{2}m_A v_A^2 \Rightarrow h_A = v_A^2/2g = 1.406 \text{ m}$   
 $h_A = L - L \cos \theta \Rightarrow \cos \theta = (L - h_A)/L = 0.2188$   
 $\rightarrow \theta = 77^\circ$