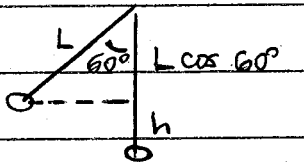


1
 3
 (a)  $L = 2.20 \text{ m} \rightarrow h = L - L \cos 60 = L/2$
 $\Rightarrow h = 1.10 \text{ m}$

4
 (b) $E_{\text{bottom}} = E_{\text{top}} \Rightarrow \frac{1}{2} m v^2 = m_B g h \Rightarrow v = \sqrt{2gh}$
 $\Rightarrow v = 4.64 \text{ m/s}$

8
 1
 (c) momentum conserv $\rightarrow m_A v_A + m_B v_B = m_B v$ (1)
 elastic collision $\rightarrow v_B - v_A = -v$ (2)

Eq(1) + $m_A \times$ Eq(2) $\rightarrow (m_A + m_B) v_B = (m_B - m_A) v$

$m_A = 0.80 \text{ kg}, m_B = 1.20 \text{ kg} \Rightarrow v_B = 0.2 v = 0.93 \text{ m/s}$

$\rightarrow v_A = v + v_B = 5.57 \text{ m/s}$

5
 1
 (d) Energy conserv $\rightarrow m_A g h_A = \frac{1}{2} m_A v_A^2 \Rightarrow h_A = v_A^2 / 2g = 1.584 \text{ m}$
 $\rightarrow h_A = L - L \cos \theta \Rightarrow \cos \theta = (L - h_A) / L = 0.280$
 $\rightarrow \theta = 74^\circ$

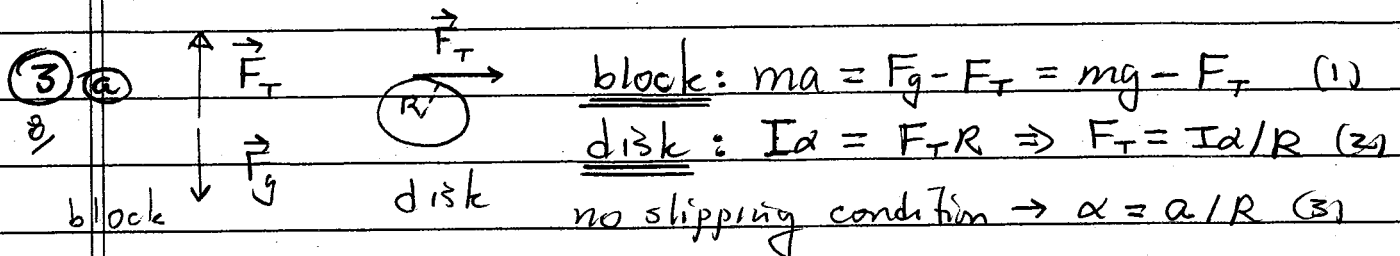
2
 4
 (a) $m = 0.14 \text{ kg}, r = 0.15 \text{ m}, v = 5.0 \text{ m/s}$
 $\Rightarrow L_m = m v r = 0.105 \text{ kg-m}^2/\text{s}$

6
 (b) Ang mom. conserv $\Rightarrow L_{\downarrow} + L_m = 0 \Rightarrow I \omega = -L_m$
 $I = 0.120 \text{ kg-m}^2 \Rightarrow \omega = -L_m / I = -0.875 \text{ rad/s}$

rotates opposite way mouse runs

11
 (c) $K_{\text{total}} = \frac{1}{2} m v^2 + \frac{1}{2} I \omega^2 = 1.75 \text{ J} + 0.046 \text{ J} \rightarrow K_{\text{total}} = 1.80 \text{ J}$

5
 (d) 4 revs $\rightarrow \Delta \theta = 4(2\pi) = 8\pi \text{ rads} \rightarrow \Delta \theta = |\omega| t$
 $\rightarrow t = \Delta \theta / |\omega| = 28.7 \text{ sec}$



Substitute eqs (2) and (3) into eq (1)
 $\rightarrow ma = mg - I\alpha/R^2 \Rightarrow a = mg / (m + I/R^2)$

$I = 0.16 \text{ kg}\cdot\text{m}^2, m = 0.50 \text{ kg}, R = 0.20 \text{ m} \rightarrow a = 1.09 \text{ m/s}^2$

3 revs $\rightarrow \Delta\theta = 3(2\pi) = 6\pi$ radians, $\alpha = a/R = 5.444 \text{ rad/s}^2$

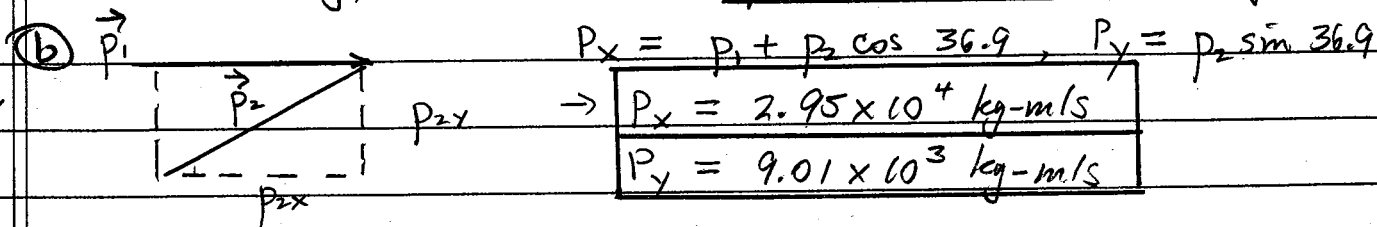
$\Delta\theta = \frac{1}{2} \alpha t^2 \Rightarrow t = \sqrt{2(\Delta\theta)/\alpha} \rightarrow t = 2.63 \text{ sec}$

Energy conserv $\Rightarrow K_{\text{tot}} = mgh = mg[3(2\pi R)] = (6\pi)mgR$
 $\rightarrow K_{\text{tot}} = 18.5 \text{ J}$

$K_{\text{trans}} = \frac{1}{2} mV^2$ and $K_{\text{rot}} = \frac{1}{2} I\omega^2 = \frac{1}{2} I(V/R)^2 = \frac{1}{2} (I/R^2) V^2$

$\frac{K_{\text{trans}}}{K_{\text{tot}}} = \frac{m}{m + I/R^2} = \frac{1}{9}$ $\frac{K_{\text{rot}}}{K_{\text{tot}}} = \frac{I/R^2}{m + I/R^2} = \frac{8}{9}$

$M_1 = 1750 \text{ kg}, V_1 = 10.0 \text{ m/s} \Rightarrow p_1 = M_1 V_1 = 1.75 \times 10^4 \text{ kg}\cdot\text{m/s}$
 $M_2 = 2500 \text{ kg}, V_2 = 6.0 \text{ m/s} \Rightarrow p_2 = M_2 V_2 = 1.50 \times 10^4 \text{ kg}\cdot\text{m/s}$



Momentum conserv $\Rightarrow \vec{P}_{\text{fin}} = \vec{P}_{\text{in}}$

$P_{\text{in}} = \sqrt{P_x^2 + P_y^2} = 3.084 \times 10^4 \text{ kg}\cdot\text{m/s} \Rightarrow V_f = P_{\text{in}} / (M_1 + M_2)$

$\rightarrow V_f = 7.26 \text{ m/s}$ $\tan\phi = P_y/P_x = 0.3053 \rightarrow \phi = 17.0^\circ$

$K_{\text{in}} = \frac{1}{2} M_1 V_1^2 + \frac{1}{2} M_2 V_2^2 = 1.325 \times 10^5 \text{ J}$

$K_{\text{fin}} = \frac{1}{2} (M_1 + M_2) V_f^2 = 1.119 \times 10^5 \text{ J}$

$K_{\text{lost}} = K_{\text{in}} - K_{\text{fin}} = 2.06 \times 10^4 \text{ J}$