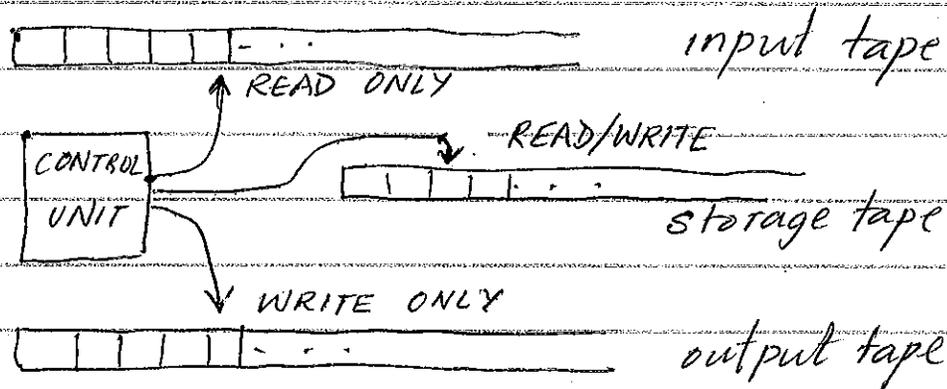


(1)

Ch.3 - Finite State Machines

§1. Deterministic Finite State Acceptors

A Finite State Machine (FSM) is an abstract model of a digital computing machine in which the device can enter into only a finite number of different states. In a finite state machine, there may be input, storage, or output tapes of finite or unlimited capacities. Information can be read from, or written on, these tapes by a control unit (which is also known as the head).



Finite state machines can be classified according to the kinds of tape they have, the kind of access to any storage tape they may have, and the mode of operation.

Def. An acceptor is an FSM with an input tape and a YES/NO output tape. (There may or may not be any storage tape.) A yes/no output tape has only one space for a "0" (NO) or a "1" (YES)

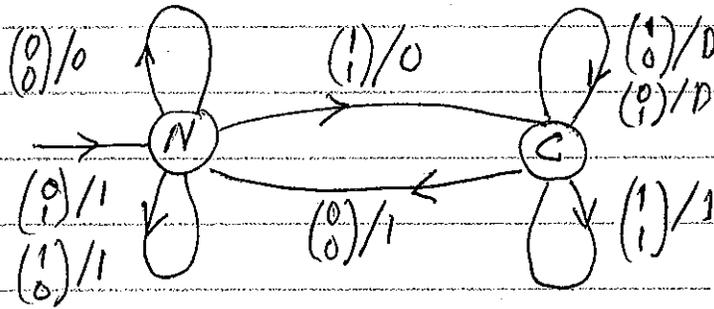
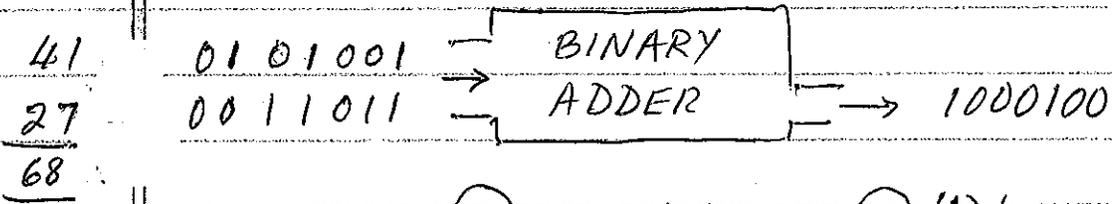
(2)

Classification of Finite State Machines

TYPE	TAPES, STORAGE PRESENT, MODE OF OPERATION
1(a) DFA Deterministic Finite Automaton	Infinite input tape, no storage tape, Yes/No output tape, Deterministic mode of operation
1(b) NFA Non-deterministic Finite Automaton	Infinite input tape, no storage tape, YES/NO output tape, Non-deterministic mode allowed.
2(a) DPDA Deterministic Push Down Automaton	Infinite input tape, infinite storage tape with stack access only, YES/NO output tape, Deterministic mode of operation.
2(b) PDA Push Down Automaton	Infinite input tape, infinite storage tape with stack access only, YES/NO output tape, Non-deterministic mode allowed
3. LBM Linear Bounded Machine	Infinite storage tape which also functions as the input & output tape, random access to a portion of the storage tape which is bounded by a constant times the size of input, Non-deterministic mode allowed.
4(a) DTM Deterministic Turing Machine	{ Infinite storage tape which functions as the input & output tape, random access to the whole of the storage tape, Deterministic mode
4(b) TM Turing Machine	

(3)

Ex.1 Suppose we want an FSM which does binary addition. How should we design it?



Input : $\begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \leftarrow \text{start here}$

Output : 1 0 0 0 1 0 0

state : N C C C N C C N $\leftarrow \text{starting state}$

Note: The FSM we got is not an acceptor but its mode of operation is deterministic. So we can call it a DFSM.

Def. A Deterministic Finite Acceptor (DFA) is a 5-tuple $M = \langle Q, T, \delta, q_0, \mathcal{A} \rangle$ where

$Q(M) = Q$ is a finite set of (internal) states

$T(M) = T$ is an alphabet called the input alphabet

$\delta_M = \delta: Q \times T \rightarrow Q$ is a function called the transition function

$q_0(M) = q_0 \in Q$ is the designated initial state, and

$\mathcal{A}(M) = \mathcal{A} \subseteq Q$ is the designated set of accepting states.

Ex.1 Let $M_1 = \langle Q, T, \delta, q_0, \mathcal{A} \rangle$ where $Q = \{A, B, C\}$, $T = \{0, 1\}$, $q_0 = A$, $\mathcal{A} = \{B\}$ and $\delta: Q \times T \rightarrow Q$ is defined by

(4)

$$\delta(A, 0) = A$$

$$\delta(A, 1) = B$$

$$\delta(B, 0) = A$$

$$\delta(B, 1) = C$$

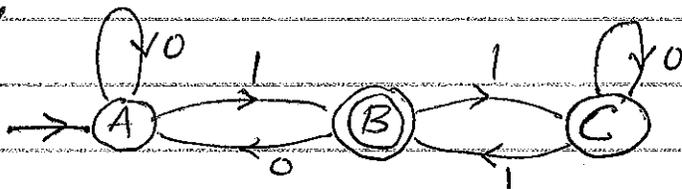
$$\delta(C, 0) = C$$

$$\delta(C, 1) = B$$

We can represent M_1 by the transition table on the right with " \rightarrow " designating the initial state & "O" designating accepting states.

$Q \setminus T$	0	1
$\rightarrow A$	A	B
ⓐ	A	C
c	C	B

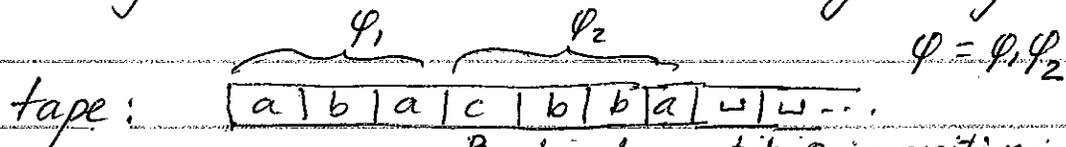
We can also represent M_1 by a transition graph with " \rightarrow " designating the initial state & ⓐ designating the accepting states.



Note:

It is possible for a state to be the initial state as well as an accepting state. If $\delta(B, a) = D$ in M we say that $B \xrightarrow{a} D$ is a transition in M .

We can describe the operation of a DFA M_1 by giving the sequence of configurations of M when it is presented with an input $\varphi \in T^*$. A configuration is an ordered pair $\langle q, \varphi_1, \varphi_2 \rangle$ where q is the control state and φ_1, φ_2 is the input string with the head under the beginning of φ_2 .



B head in state B in position indicate

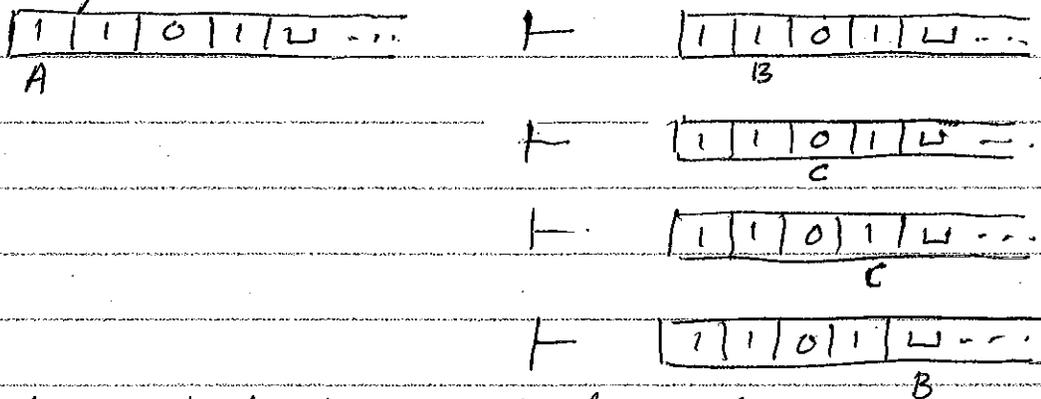
configuration: $\langle B, \underbrace{a|b|a}_{\varphi_1} \underbrace{c|b|b|a}_{\varphi_2} \rangle$ $\sqcup =$ blank symbol

5

Let us run the DFA M_1 of Ex. 1 with $\varphi = 1101$ as input. When the head reaches a " \sqcup " M_1 will halt.

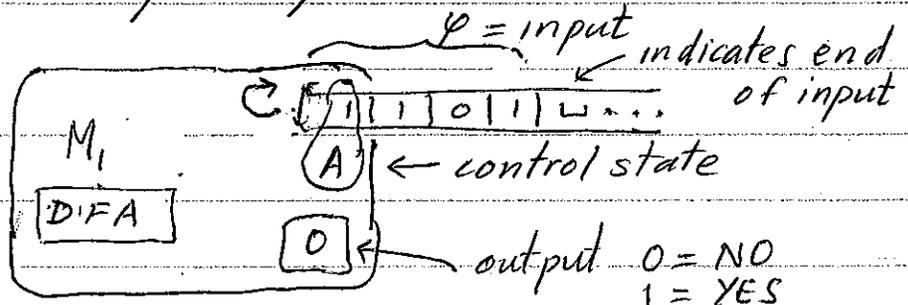
$\langle A, \underline{1}101 \sqcup \rangle \vdash \langle B, 1\underline{1}01 \sqcup \rangle$
 $\vdash \langle C, 11\underline{0}1 \sqcup \rangle$
 $\vdash \langle C, 110\underline{1} \sqcup \rangle$
 $\vdash \langle B, 1101\underline{\sqcup} \rangle$

The tapes will look as shown below:



Notice that the input does not change - we simply move into a control state with each character of the input and stop (halt) as soon as we reach the blank symbol " \sqcup ". If the last control state we reach is an accepting state, we say that the DFA accepts the input; if it is not an accepting state, we say that the DFA rejects the input.

So 1101 is accepted by the DFA M_1 in Ex. 1



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Note: In a DFA we are only allowed to input a single string φ from T^* . The " \sqcup " cannot be a part of the input alphabet T . Instead of showing the sequence of configurations of the DFSA M_1 on an input φ (or the sequence of tapes) we can just show what happens using two rows as shown below.

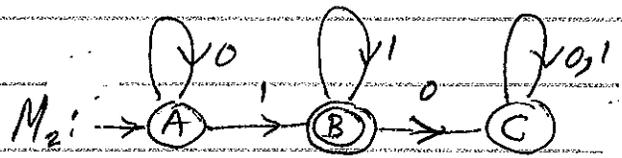
input characters : 1 1 0 1 \sqcup
 control states : A B C C B

Let us try another input, say $\psi = 100$ on M_1 .

input : 1 0 0 \sqcup
 states : A B A A

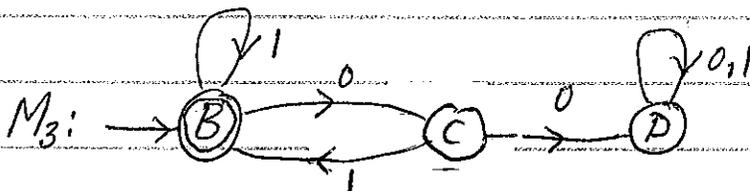
Since A is not an accepting state, 100 is not accepted by M . We will define $L(M)$ to be the set of all strings in T^* which are accepted by M_1 .

Ex.2 Let M_2 be the DFA shown on the right. Find $L(M_2)$.



$$L(M_2) = \underline{0^*} \underline{11}^*$$

Ex.3 Let M_3 be the DFA. show below. Find $L(M_3)$



$$L(M_3) = (\underline{1} + \underline{01})^*$$

7

We will now define precisely what it means for a DFA M to accept a string φ and precisely what is $L(M)$.

Def. The extended transition function $\delta^* : Q \times T^* \rightarrow Q$ of a DFA is defined recursively as follows.

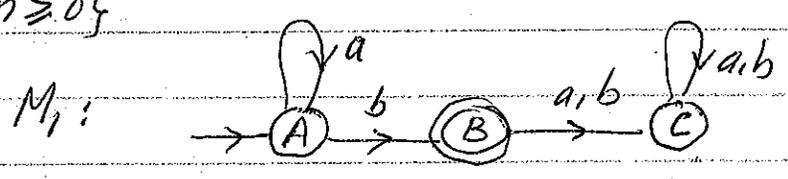
(a) $\delta^*(q, \lambda) = q$

(b) $\delta^*(q, \varphi c) = \delta(\delta^*(q, \varphi), c)$ for each $c \in T$.

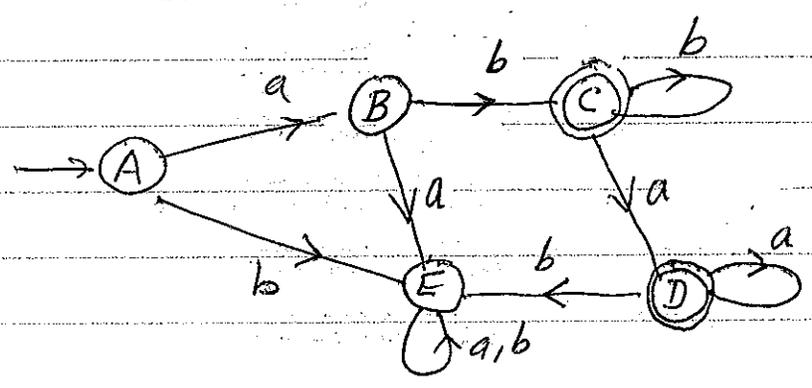
Def. The string $\varphi \in T^*$ is said to be accepted by a DFSA M if $\delta^*(q_0, \varphi) \in A(M)$. The string φ is rejected by M if $\delta^*(q_0, \varphi) \notin A(M)$.

Def. The language recognized by a DFA M is defined by $L(M) = \{\varphi \in T^* : \delta^*(q_0, \varphi) \in A(M)\}$.

Ex.1 Find a DFA M_1 , which recognizes the language $L_1 = \{a^n b : n \geq 0\}$



Ex.2 Find a DFSA M_2 which recognizes the language $L_2 = a b^* b a^*$ Hint: $a b^* b a^* = a b b^* a^*$



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Ex. 3

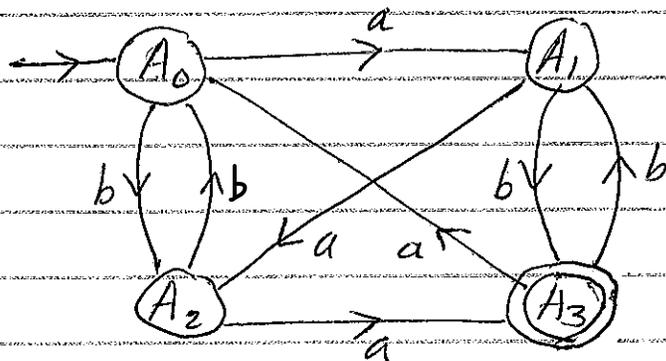
Let $n_a(w)$ = number of a's in w and $n_b(w)$ = the number of b's in w . Find a DFA which recognizes the language

$$L_3 = \{w \in \{a,b\}^* : n_a(w) + 2n_b(w) \equiv 3 \pmod{4}\}.$$

Let the states be A_0, A_1, A_2 , and A_3 and let $f(w) = n_a(w) + 2n_b(w)$. We will use A_i to keep track of the fact that when the initial part φ of w is processed, the value of $f(\varphi) \equiv i \pmod{4}$. Since $f(\lambda) = 0$, the initial state will be A_0 . Also when $f(\varphi) \equiv 3 \pmod{4}$ φ will be accepted, so A_3 is the only accepting state. Now

$$f(\varphi a) = n_a(\varphi a) + 2n_b(\varphi a) \equiv n_a(\varphi) + 2n_b(\varphi) + 1 = f(\varphi) + 1 \pmod{4}$$
$$\& f(\varphi b) = n_a(\varphi b) + 2n_b(\varphi b) \equiv n_a(\varphi) + 2n_b(\varphi) + 2 = f(\varphi) + 2 \pmod{4}$$

So $M_3 =$



Ex 4

Show what happens when $w = ababa$ is used as the input to the DFA: M_3 and verify your answer using modulo arithmetic.

input: a b a b a \sqcup

states: $A_0 A_1 A_3 A_0 A_2 A_3$ So $w \in L(M_3)$

Check: $f(w) = n_a(w) + 2n_b(w) = 3 + 2(2) = 7 \equiv 3 \pmod{4}$

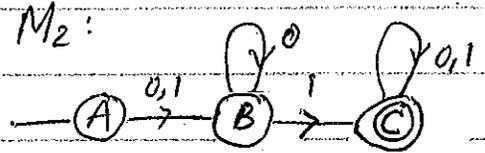
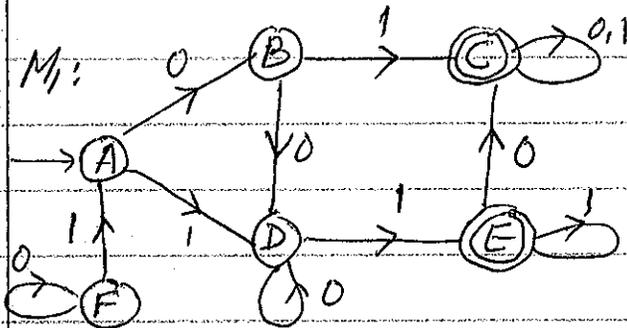
Since $w \in L_3$, w should be accepted by M_3 .

(9)

§2. The Partition Algorithm & Minimal DFSA's

Def. Two DFA's M_1 and M_2 are said to be equivalent if $L(M_1) = L(M_2)$.

Ex.1 Consider the two DFA's M_1 & M_2 below



It is not difficult to see that

$$L(M_1) = (0+1) \cdot 0^* \cdot 1 \cdot (0+1)^* = L(M_2). \text{ So } M_1 \equiv M_2.$$

But it is clear that M_2 is much simpler than M_1 . We will later see M_2 is the DFSA with the smallest number of states which is equivalent to M_1 .

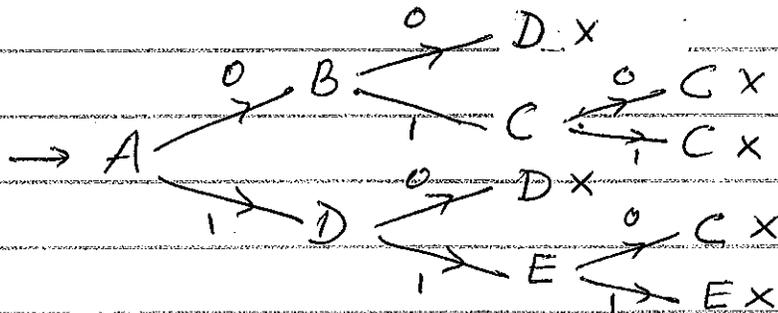
Def. A state q in a DFA. M is said to be inaccessible if there is no string $w \in T^*$ such that $\delta^*(q_0, w) = q$.

In other words, q is inaccessible if we can never reach it from the initial state. In M_1 , the state F is inaccessible because there is no way to get from A to F .

Ex.2 How can we find all the inaccessible states in the DFSA M_1 of Ex.1

(10)

Ans: Start with the initial state of M and keep branching out with each character of T . When a previously accessible state is reached, discontinue that branch. The accessible states of M will be all the states in the accessibility tree.



So the acc. states are $A, B, C, D, \& E$. $\therefore F$ is inacc.

To find the DFA M_R which is equivalent to a given DFA M , we will remove the inaccessible states and get rid of the redundant states.

Def. Two states p & q in a DFA, M , are indistinguishable if for each string $\varphi \in T^*$ we have

$$S^*(p, \varphi) \in A(M) \iff S^*(q, \varphi) \in A(M)$$

So indistinguishable states are in a sense equivalent. Also if p_1, p_2, \dots, p_k are indistinguishable states which are all accessible in M , then we need only one of them, p_1 say, and the rest will all be redundant.

In M , the states B & D are indistinguishable. Also C & E are indistinguishable. So if we keep B and C , then D and E will be redundant & can be removed.

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In removing a redundant state, we have to make sure that we replace it by an equivalent one.

The Partition Algorithm for DFA

Input: The set of states of a DFA M

Output: Blocks of indistinguishable states of M

1. Start with the initial partition P_0 consisting of 2 blocks

$P_0: Q - A, A$. Then let $n \leftarrow 0$.

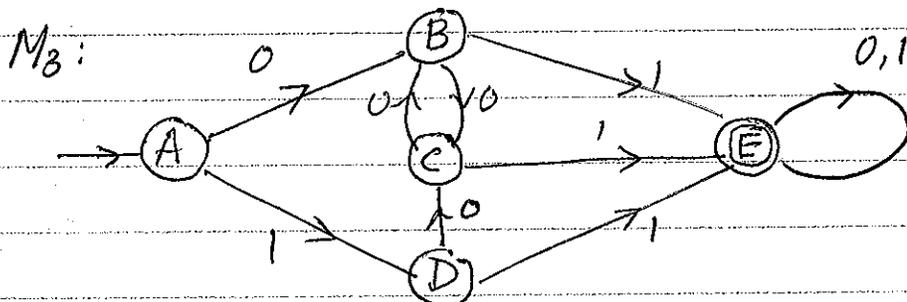
2. Two states p and q in the same block of P_n will stay together in the same block of P_{n+1} if for each $c \in T$, $\delta(p, c)$ & $\delta(q, c)$ belong to the same block of P_n .

If for at least one $c \in T$, $\delta(p, c)$ & $\delta(q, c)$ belong to different blocks of P_n , then p & q will split and go into different blocks of P_{n+1} .

3. If $P_{n+1} = P_n$, then STOP. (P_n will be the final partition of Q into blocks of indistinguishable states)
Otherwise, let $n \leftarrow n+1$; and go to step 2.

Ex.3

Partition the states of the DFA M_3 into blocks of indistinguishable states.



Notice that all the states in M_3 are accessible.

(12)

1. $P_0 : \{A, B, C, D\} \{E\}$
 $A \xrightarrow{0} B \in 1st \text{ block of } P_0, \quad A \xrightarrow{1} D \in 1st \text{ block of } P_0$
 $B \xrightarrow{0} C \in 1st \text{ block of } P_0, \quad B \xrightarrow{1} E \in 2nd \text{ block of } P_0$
 $C \xrightarrow{0} B \in 1st \text{ block of } P_0, \quad C \xrightarrow{1} E \in 2nd \text{ block of } P_0$
 $D \xrightarrow{0} C \in 1st \text{ block of } P_0, \quad D \xrightarrow{1} E \in 2nd \text{ block of } P_0$

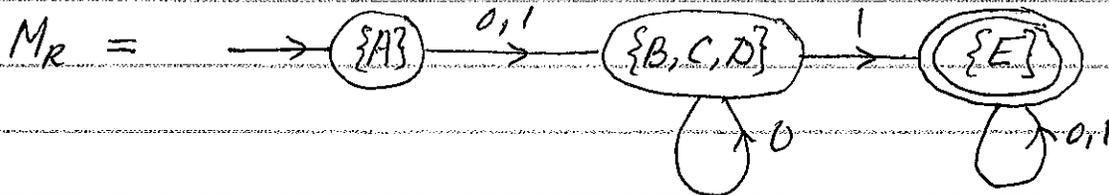
2. $P_1 : \{A\} \{B, C, D\} \{E\}$
 $B \xrightarrow{0} C \in 2nd \text{ block of } P_1, \quad B \xrightarrow{1} E \in 3rd \text{ block of } P_1$
 $C \xrightarrow{0} B \in 2nd \text{ block of } P_1, \quad C \xrightarrow{1} E \in 3rd \text{ block of } P_1$
 $D \xrightarrow{0} C \in 2nd \text{ block of } P_1, \quad D \xrightarrow{1} E \in 3rd \text{ block of } P_1$

3. $P_2 : \{A\} \{B, C, D\} \{E\}$.

Since $P_2 = P_1$, P_1 is the final partition of Q into blocks of indistinguishable states.

Ex 4 Find the minimal (or reduced) DFA: M_R that is equivalent to the DFA: M_3 in Ex. 3.

We will use each block of the final partition as a state in M_R . The initial state will be the one that contains the initial state of M_3 . The accepting states will be the blocks which consists only of accepting states



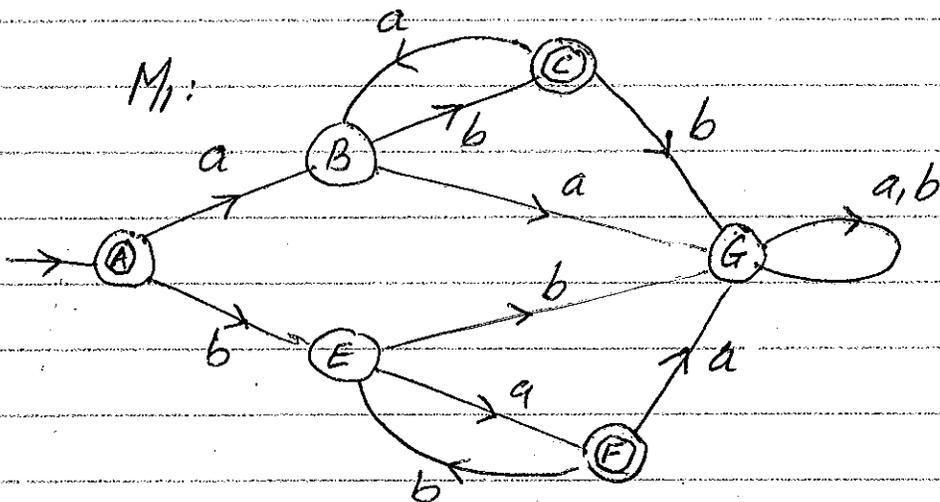
Some textbooks like to pick one representative each to get

but we prefer using the blocks.

Note: $L(M_3) = L(M_R) = (0+1).0^*.1.(0+1)^*$.

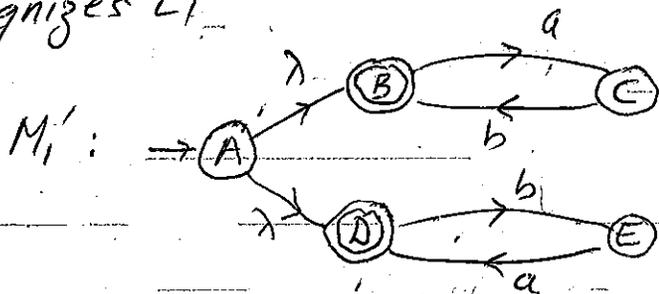
§3. Non-deterministic Finite Acceptor

Ex.1 Find a DFA which recognizes the language $L_1 = (ab)^* + (ba)^*$



Although L_1 appears to be a rather simpler language, the DFA M_1 is decidedly complex.

If we generalize the concept of a DFA and allow non-deterministic mode of operation, we can get a much simpler acceptor M_1' which recognizes L_1 .



We can jump from A to B with the empty string λ and go around the loop from B to C to recognize $(ab)^*$ - but we can't go back to A from B and

try to reach D . We can jump with λ from A to D and go around the loop from D to E to recognize the second part $(ba)^*$ - but again we cannot go back to A from D . So $L(M_1') = L_1$.

Note: In the NFA M_1' , $A \xrightarrow{\lambda} B$ & $A \xrightarrow{\lambda} D$ are transitions which are called lambda-transitions. Also if we reach C and the next character is an "a" then we cannot move and we say that the NFA crashes. (The NFA M will accept a string φ only if there is some way to reach the first blank symbol \sqcup after φ and do so in an accepting state). Also for each state X , the transition $X \xrightarrow{\lambda} X$ is present but not shown. Let us see what happens if baba is the input to the NFA M_1' .

$\rightarrow A \xrightarrow{\lambda} B \xrightarrow{b}$ crashes rejected by crashing
 $\rightarrow A \xrightarrow{\lambda} D \xrightarrow{b} E \xrightarrow{a} D \xrightarrow{b} E \xrightarrow{a} D$ accepted

Let us also see what happens if aba is the input

$\rightarrow A \xrightarrow{\lambda} B \xrightarrow{a} C \xrightarrow{b} B \xrightarrow{a} C$ properly rejected
 $\rightarrow A \xrightarrow{\lambda} D \xrightarrow{a}$ crashes rejected by crashing

Finally let us look at the input abb

$\rightarrow A \xrightarrow{\lambda} B \xrightarrow{a} C \xrightarrow{b} B \xrightarrow{b}$ crashes, rejected by crashing
 $\rightarrow A \xrightarrow{\lambda} D \xrightarrow{a}$ crashes rejected by crashing

So M_1' accepts baba and rejects aba & abb.

(16)

In other words, a string is accepted if there is at least one way of it being accepted. Observe that the string λ , is accepted along two paths & rejected along one path.

$A \xrightarrow{\lambda} A$ rejected because $A \notin \mathcal{A}(M_1')$

$A \xrightarrow{\lambda} B$ accepted because $B \in \mathcal{A}(M_1')$

$A \xrightarrow{\lambda} D$ accepted because $D \in \mathcal{A}(M_1')$.

We will now define precisely what is an NFA and also define what is $L(M)$ for an NFA M .

Def. A Non-deterministic Finite Acceptor (NFA) is a 5-tuple $M = \langle Q, T, \Delta, q_0, \mathcal{A} \rangle$ where Q, T, q_0 , and \mathcal{A} are as in a DFA and $\Delta \subseteq [Q \times (T \cup \{\lambda\})] \times Q$ is a binary relation from $Q \times (T \cup \{\lambda\})$ to Q .

We interpret the ordered pair $\langle (q_1, c), q_2 \rangle$ as meaning that c can lead you from q_1 to q_2 . We sometimes write the ordered pair $\langle (q_1, c), q_2 \rangle$ as the expression $q_1 \xrightarrow{c} q_2$ and call it a transition. If $c = \lambda$, and $q_1 \neq q_2$, we call $q_1 \xrightarrow{\lambda} q_2$ a λ -transition.

Note also that if the relation Δ turns out to be a total function from $Q \times (T \cup \{\lambda\})$ to Q , then the NFA will actually be a DFA. The extended transition relation Δ^* is the set of all ordered pairs $\langle (q_1, \varphi), q_2 \rangle$ such that φ can lead you from q_1 to q_2 .

(17)

Def Let $\varphi \in T^*$ and M be an NFA. We say that φ is accepted by M if we can find a sequence of transitions $q_0 \xrightarrow{c_1} q_1 \xrightarrow{c_2} q_2 \xrightarrow{c_3} \dots \xrightarrow{c_n} q_n$ such that $c_1 c_2 \dots c_n = \varphi$ and $q_n \in \mathcal{A}(M)$.

Here each $c_i \in T \cup \{\lambda\}$. (In other words φ is accepted by M if $\langle (q_0, \varphi), q_F \rangle \in \Delta^*$ for some $q_F \in \mathcal{A}(M)$.)

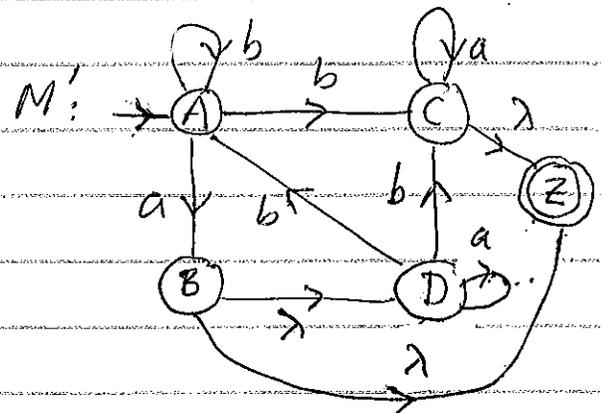
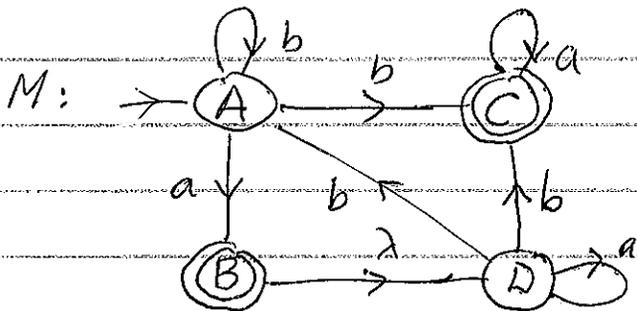
The language recognized by an NFA is defined by $L(M) = \{\varphi \in T^* : \varphi \text{ is accepted by } M\}$.

Def A One-accepting-state NFA (OAS-NFA) is an NFA which has exactly one accepting state which is different from the initial state

Prop.1 Any NFA M is equivalent to an OAS-NFA M' .

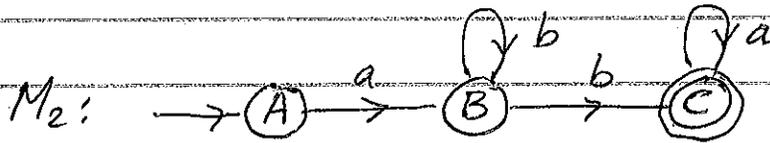
Proof. Let $Q(M') = Q(M) \cup \{z\}$, where z is a new state that is not already in $Q(M)$. Then add λ -transitions from each state in $\mathcal{A}(M)$ to z . Finally let $\mathcal{A}(M') = \{z\}$. Then it can be shown that $L(M') = L(M)$. So $M' \equiv M$.

Ex.2 Find an OAS-NFA M' which is equivalent to the NFA M shown below.



(18)

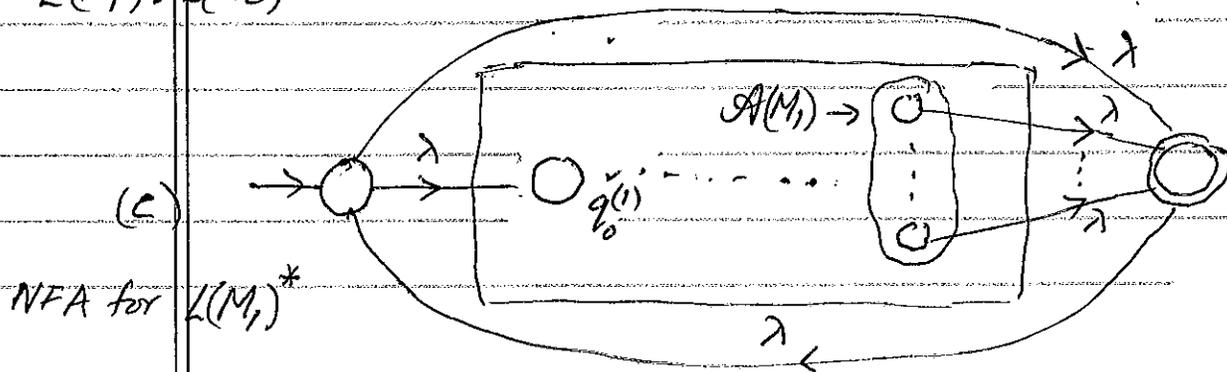
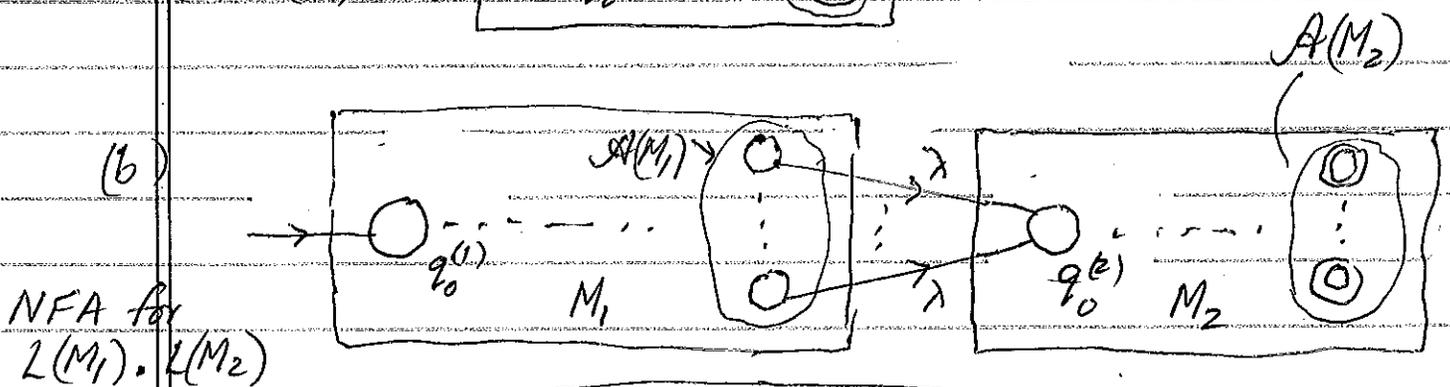
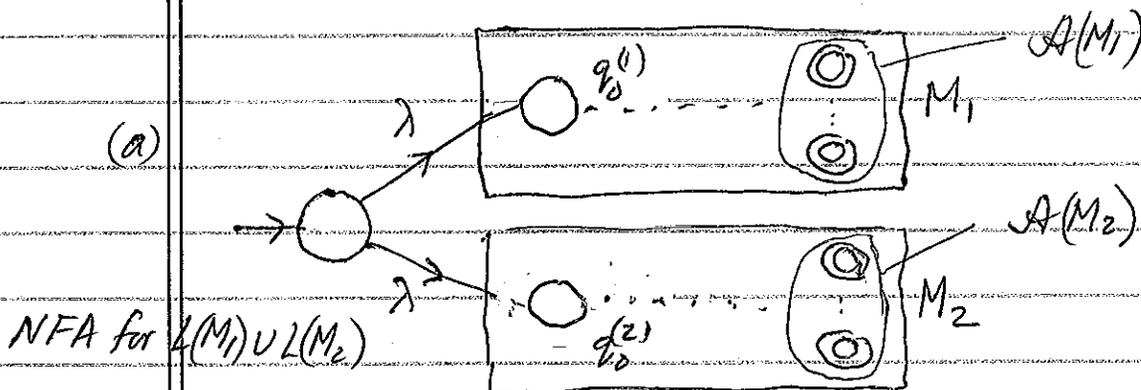
Ex 2. Find an NFA which recognizes the language $L_2 = \underline{a} b^* \underline{b} a^*$



If you try to find a DFA which recognizes L_2 , then you will begin to appreciate how "user friendly" NFAs are.

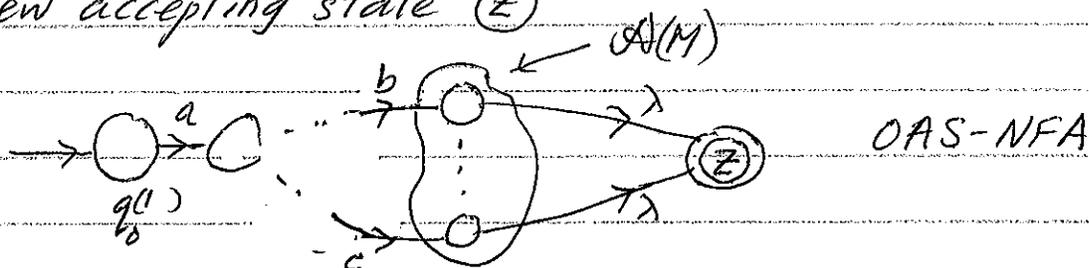
Qu. 1 Given NFAs M_1 & M_2 , how can we find NFAs which can recognize

- (a) $L(M_1) \cup L(M_2)$ (b) $L(M_1) \cdot L(M_2)$ (c) $L(M_1)^*$ (d) $L(M_1)^R$.

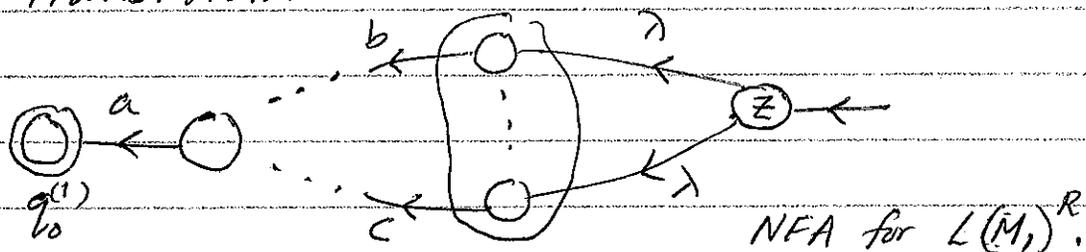


(19)

(d) First convert M_1 into an OAS-NFA by adding a new accepting state Z



Then make Z into the initial state, $q_0^{(1)}$ into the only accepting state, and reverse the direction of each transition.



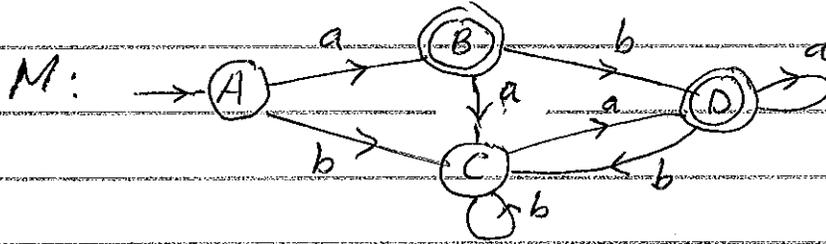
Now if we try to answer Qu. 1 with DFAs replacing NFAs, then it will not at all be easy. That is because DFAs are not very easy to combine. But there is one thing that we can do with DFAs that we cannot easily do with NFAs.

Prop 2: Let $M = \langle Q, T, \delta, q_0, A(M) \rangle$. Put $M_c = \langle Q, T, \delta, q_0, Q - A(M) \rangle$. Then $L(M_c) = L(M)^c$

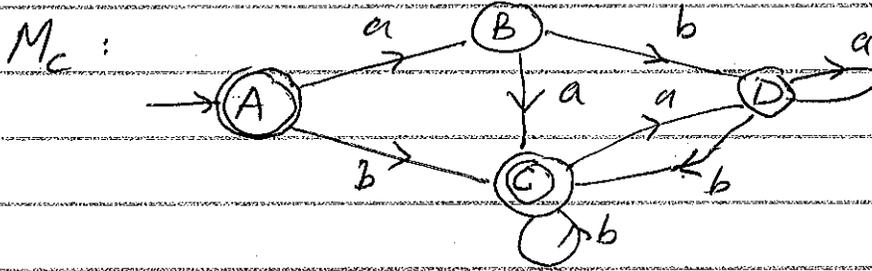
Proof: $w \in L(M_c) \Leftrightarrow \delta^*(q_0, w) \in Q - A(M)$
 $\Leftrightarrow \delta^*(q_0, w) \notin A(M)$
 $\Leftrightarrow w \notin L(M)$.

So $L(M_c) = L(M)^c$ and we are done.

Ex. 3 Find a DFA M_c such that $L(M_c) = L(M)^c$ where M is the DFA shown below.



Ans:

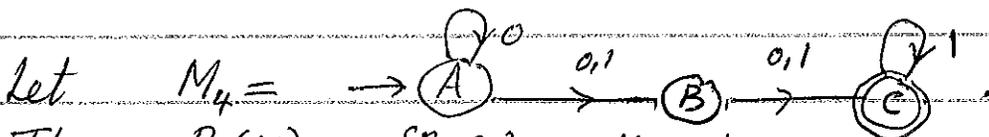


We cannot do this with NFAs because Prop 2 does not hold for NFAs. Fortunately, we can show, in the next section, that every NFA is equivalent to a DFA and this will help us.

§4. Equivalence of NFAs & DFAs.

Def. Let M be an NFA and $\varphi \in T^*$. The reaching set $R(\varphi)$ of φ in M is defined as follows.
 $q_n \in R(\varphi)$ if and only if there is a sequence of transitions $q_0 \xrightarrow{c_1} q_1 \xrightarrow{c_2} q_2 \dots q_{n-1} \xrightarrow{c_n} q_n$ with $c_1 c_2 \dots c_n = \varphi$ and each $c_i \in T \cup \{\lambda\}$.

Ex. 4



Then $R(01) = \{B, C\}$ in M_4 because

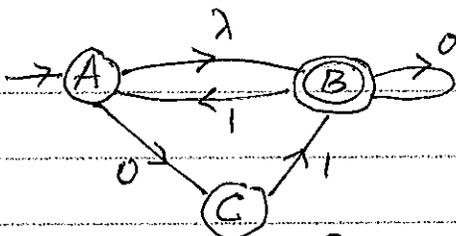
$$\rightarrow A \xrightarrow{0} A \xrightarrow{1} B \quad \& \quad \rightarrow A \xrightarrow{0} B \xrightarrow{1} C$$

Also $R(00) = \{A, B, C\}$ in M_4 because

$$\rightarrow A \xrightarrow{0} A \xrightarrow{0} A, \quad \rightarrow A \xrightarrow{0} A \xrightarrow{0} B, \quad \rightarrow A \xrightarrow{0} B \xrightarrow{0} C.$$

(21)

Ex.5

Let $M_s =$ 

Then

- (a) $R(\lambda) = \{A, B\}$ because $\rightarrow A \xrightarrow{\lambda} A, \rightarrow A \xrightarrow{\lambda} B$
- (b) $R(0) = \{B, C\}$ because $\rightarrow A \xrightarrow{\lambda} B \xrightarrow{0} B, \rightarrow A \xrightarrow{0} C.$
- (c) $R(00) = \{B\}$ because $\rightarrow A \xrightarrow{\lambda} B \xrightarrow{0} B \xrightarrow{0} B.$

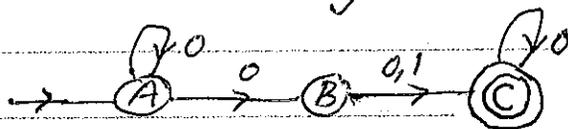
The NFA to DFA Algorithm

Input: An NFA, $M = \langle Q, T, \Delta, q_0, \mathcal{A} \rangle$

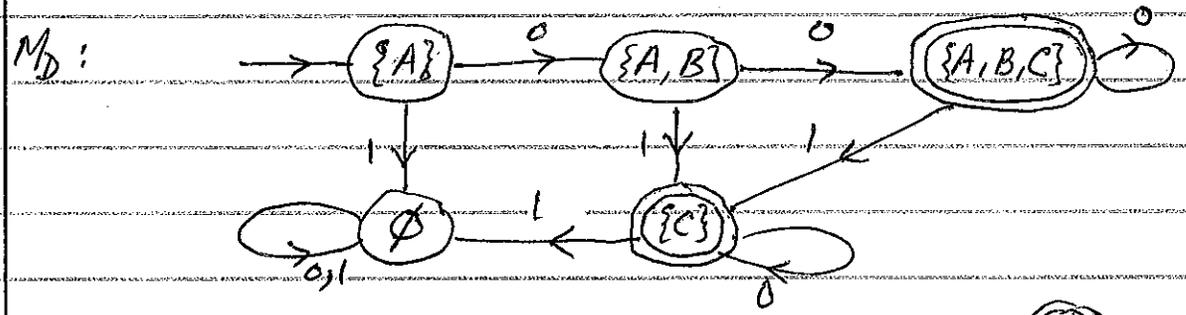
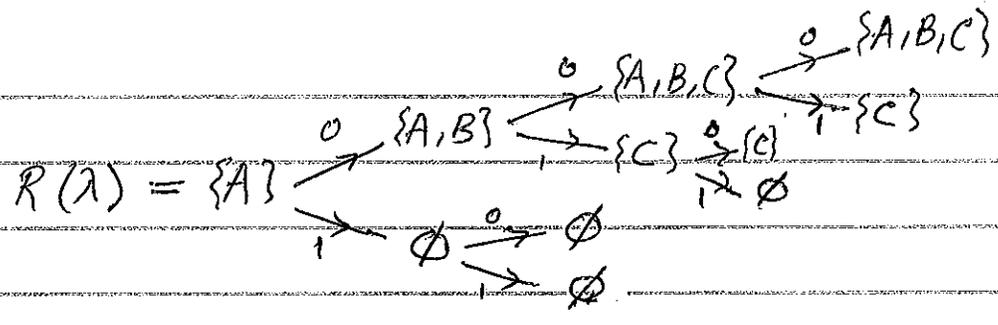
Output: An equivalent DFA, $M_D = \langle Q_D, T, \delta, R(\lambda), \mathcal{A}_D \rangle$

1. First find all possible reaching sets by starting with $R(\lambda)$ and branching out with each character in T . When a previous reaching set is encountered, that branch is discontinued. This process will give us the reaching set tree.
2. Let $Q_D = \{R(\varphi) : \varphi \in T^*\}$ = set of all reaching sets, initial state of $M_D = R(\lambda)$, and $\mathcal{A}_D = \{R(\varphi) : R(\varphi) \cap \mathcal{A}(M) \neq \emptyset\}$ = set of all reaching sets with at least one accepting state of M .
3. The transition function $\delta : Q_D \times T \rightarrow Q_D$ is specified by $\delta(R(\varphi), c) = R(\varphi c)$ for each $c \in T$, and can be read off from the reaching set tree.

Ex.6

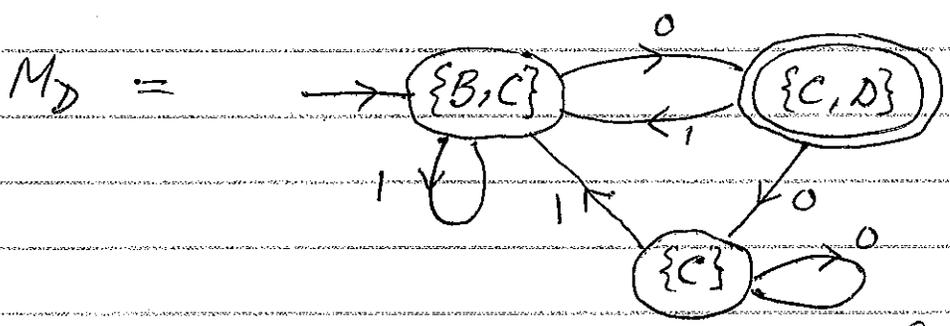
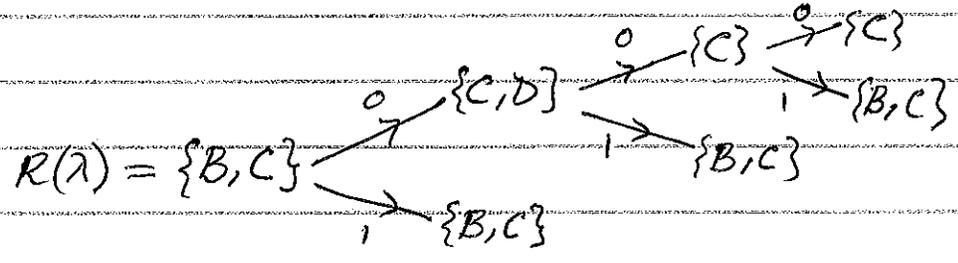
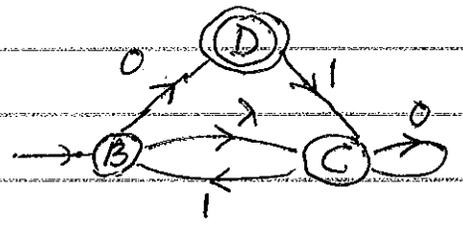
Let M be the NFAFind the equivalent DFA, M_D .

Ex. 6



Ex 7

Let M be the NFA on the right. Find the equivalent DFA, M_D .



Qu. 2

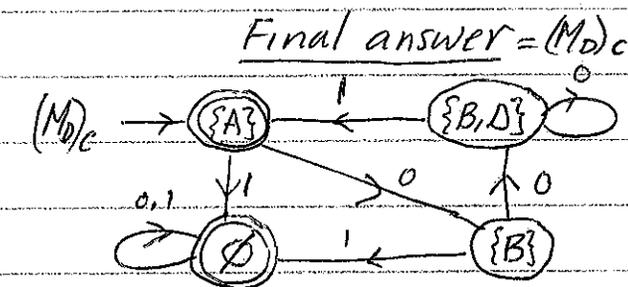
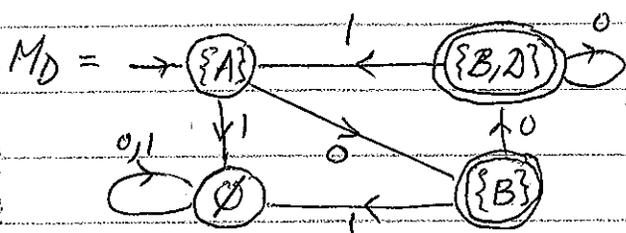
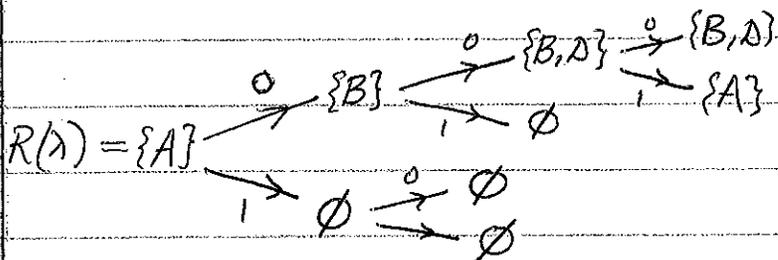
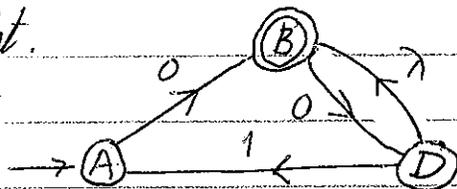
Given an NFA, M , how can we find an NFA which recognizes the language $L(M)^c$?

Ans: First convert M into an equivalent DFA M_D . Then switch the accepting & non-accepting states of M_D to get a DFA $(M_D)^c$. This will be your answer because $(M_D)^c$ is also an NFA.

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Ex. 8

Let M be the NFA on the right. Find an NFA which recognizes the language $L(M)^c$.



Theorem 3: Let $M = (Q, T, \Delta, q_0, A)$ be any NFA and $M_D = (Q_D, T, \delta, R(\lambda), A_D)$ be the DFA obtained from the NFA to DFA algorithm. Then $L(M_D) = L(M)$.

Proof:

$w \in L(M_D) \Leftrightarrow w$ can lead you from $R(\lambda)$ in M_D to an accepting state R_A in A_D

$\Leftrightarrow w$ can lead you from q_0 in M to an accepting state q_A in A (because $R(\lambda) =$ all states you can reach from q_0 using λ , and R_A is an accepting state of M_D if & only if R_A contains at least one accepting state q_A of M).

$\Leftrightarrow w \in L(M)$.

So $L(M_D) = L(M)$.

END OF Ch. 3.