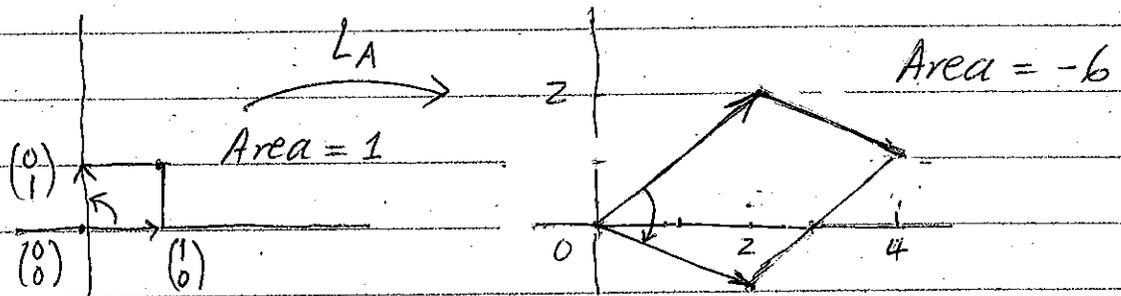


Ch 7 - Simplified representations of linear maps ①

§1. Eigenvalues & their corresponding eigenvectors

Consider the matrix $A = \begin{bmatrix} 2 & 2 \\ 2 & -1 \end{bmatrix}$. We know that A determines a linear map $L_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that is defined by $L_A(x) = Ax$. We can also get an idea of what L_A does by looking at the image of the unit square in \mathbb{R}^2 .



From the image, we can see that $\det(A) = -6$. The linear map L_A has many different representations and some of these representations can be obtained by considering the matrices $P^{-1}AP$ where P is an invertible matrix. In order to find the simplest representation of L_A , we will introduce the concepts of eigenvalues and eigenvectors of A . Before we do this we need to extend the range of possible matrices P by discussing vector spaces over \mathbb{C} .

Def. Let \mathbb{C} = the set of complex numbers. A vector space over \mathbb{C} is defined in the same way as a vector space over \mathbb{R} , except that the scalars are now from the field \mathbb{C} (instead of \mathbb{R}). An $m \times n$ matrix over \mathbb{C} is one with entries from \mathbb{C} . We use $\mathbb{C}^{m \times n}$ to denote the set of all complex $m \times n$ matrices.

Def. Let $z = a + ib$ be a complex number. The complex conjugate of z is defined by $\bar{z} = a - ib$.
 If $\underline{v} \in \mathbb{C}^n$ is a complex vector, we define the length of \underline{v} by $\|\underline{v}\| = \sqrt{\underline{v}^T \bar{\underline{v}}}$ where $\bar{\underline{v}} = \begin{pmatrix} \bar{v}_1 \\ \vdots \\ \bar{v}_n \end{pmatrix}$. We also define $\underline{v} \cdot \underline{w} = \underline{v}^T \bar{\underline{w}}$. Note that $\underline{w} \cdot \underline{v} = \underline{w}^T \bar{\underline{v}} = \bar{\underline{v}}^T \underline{w} = \overline{\underline{v} \cdot \underline{w}}$. (2)

Ex. 1 Let $\underline{v} = \begin{pmatrix} 1+i \\ 2-i \end{pmatrix}$. Then $\bar{\underline{v}} = \begin{pmatrix} 1-i \\ 2+i \end{pmatrix}$. So

$$\begin{aligned} \|\underline{v}\|^2 &= \underline{v}^T \bar{\underline{v}} = \begin{pmatrix} 1+i & 2-i \end{pmatrix} \begin{pmatrix} 1-i \\ 2+i \end{pmatrix} = (1+i)(1-i) + (2-i)(2+i) \\ &= (1-i^2) + (2-i^2) = [1-(-1)] + [2-(-1)] = (2)(3) = 6. \\ \therefore \|\underline{v}\| &= \sqrt{6}. \end{aligned}$$

Def. Let A be an $n \times n$ matrix. We say that $\lambda \in \mathbb{C}$ is an eigenvalue of A if we can find a non-zero vector $\underline{v} \in \mathbb{C}^n$ such that $A\underline{v} = \lambda \underline{v}$. The non-zero vector \underline{v} is called an eigenvector of A belonging to the eigenvalue λ .

Qu: How can we find all the eigenvalues of A ?

Sol. Suppose $A\underline{v} = \lambda \underline{v}$ & $\underline{v} \neq 0$. Then $A\underline{v} = \lambda I \underline{v}$. So $(\lambda I - A)\underline{v} = 0$. Since $\underline{v} \neq 0$, it follows that $(\lambda I - A)$ cannot be invertible. Hence $\det(\lambda I - A) = 0$. So all possible eigenvalues can be found by solving the equation $\det(\lambda I - A) = 0$ for λ .

Ex 2 Let $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$. Find all the eigenvalues of A and the corresponding eigenvectors. (3)

Sol. Suppose $\det(\lambda I - A) = 0$. Then $\begin{vmatrix} \lambda - 0 & 1 \\ -1 & \lambda - 0 \end{vmatrix} = 0$

$$\text{So } \lambda^2 - (-1) = 0. \quad \therefore \lambda^2 + 1 = 0. \quad \therefore \lambda = \pm i$$

So the possible eigenvalues are $\lambda_1 = i$ & $\lambda_2 = -i$

(a) Suppose $\lambda_1 = i$ is really an eigenvalue. Then

$(\lambda_1 I - A)x = 0$ for some non-zero vector x . So

$$\begin{bmatrix} i & 1 \\ -1 & i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \therefore \begin{aligned} ix_1 + x_2 &= 0 & \text{(1)} \\ -x_1 + ix_2 &= 0 & \text{(2)} \end{aligned}$$

Multiplying (1) by i gives us

$$i^2 x_1 + ix_2 = 0 \quad \therefore -x_1 + ix_2 = 0 \quad \therefore x_1 = ix_2$$

$$-x_1 + ix_2 = 0 \quad -x_1 + ix_2 = 0 \quad x_2 = \alpha$$

So $\begin{pmatrix} i\alpha \\ \alpha \end{pmatrix} = \alpha \begin{pmatrix} i \\ 1 \end{pmatrix}$ will be an eigenvector if $\alpha \neq 0$.

Thus $\lambda_1 = i$ is really an eigenvalue of A .

(b) Suppose $\lambda_2 = -i$ is also an actual eigenvalue.

Then $(\lambda_2 I - A)x = 0$ for some non-zero vector x

$$\text{So } \begin{bmatrix} -i & 1 \\ -1 & -i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \therefore \begin{aligned} -ix_1 + x_2 &= 0 & \text{(1)} \\ -x_1 - ix_2 &= 0 & \text{(2)} \end{aligned}$$

Multiplying (1) by $-i$ gives us

$$i^2 x_1 - ix_2 = 0 \quad \therefore -x_1 - ix_2 = 0 \quad \therefore x_1 = -ix_2$$

$$-x_1 - ix_2 = 0 \quad -x_1 - ix_2 = 0 \quad x_2 = \beta$$

So $\begin{pmatrix} -i\beta \\ \beta \end{pmatrix} = \beta \begin{pmatrix} -i \\ 1 \end{pmatrix}$ will be an eigenvector if $\beta \neq 0$

Thus $\lambda_2 = -i$ is really an eigenvalue of A

§2 Properties of eigenvalues & eigenvectors

(24)

Prop. 1: Let A be an $n \times n$ matrix. Then A has n eigenvalues (counting multiplicities).

Proof: Suppose λ is an eigenvalue of A . Then $\det(\lambda I - A) = 0$. Now $\det(\lambda I - A)$ is a polynomial in λ of degree n . So $\det(\lambda I - A)$ will have n roots (counting multiplicities). Now each of these roots λ_i will indeed be an eigenvalue because if $\det(A - \lambda_i I) = 0$, then the system $(\lambda_i I - A)x = 0$ will always have a non-trivial solution which will turn out to be an eigenvector corresponding to the eigenvalue λ_i . So A will have n eigenvalues (counting multiplicities).

Prop. 2: Suppose x_1 & x_2 are eigenvectors of A corresponding to different eigenvalues λ_1 and λ_2 . Then the eigenvectors x_1 & x_2 are linearly independent.

Proof: Suppose x_1 & x_2 are eigenvectors of A corresponding to different eigenvalues λ_1 & λ_2 .

Then $Ax_1 = \lambda_1 x_1$ and $Ax_2 = \lambda_2 x_2$.

Now suppose $\{x_1, x_2\}$ is linearly dependent.

Then $x_1 = cx_2$ for some $c \neq 0$ because $x_1, x_2 \neq 0$. So

$$\lambda_1 x_1 = Ax_1 = A(cx_2) = c(Ax_2) = c(\lambda_2 x_2) = \lambda_2 (cx_2) = \lambda_2 x_1$$

Hence $(\lambda_1 - \lambda_2)x_1 = 0$. Since $\lambda_1 \neq \lambda_2$, we must have $x_1 = 0$

which contradicts the fact that x_1 was an eigenvector of A . Hence x_1 & x_2 must be linearly independent.

Def. Let A be any $n \times n$ matrix. Then $\det(\lambda I - A)$ is a monic polynomial in λ of degree n in λ . It is called the characteristic polynomial $P_A(\lambda)$ of A . The equation $\det(\lambda I - A) = 0$ is called the characteristic equation of A .

Def. If λ is an eigenvalue of A , then we define the eigenspace $E_\lambda(A)$ by $E_\lambda(A) = \{x \in \mathbb{C}^n : Ax = \lambda x\}$. Note that $0 \in E_\lambda(A)$ and that all the non-zero vectors in $E_\lambda(A)$ will be eigenvectors corresponding to λ . The geometric multiplicity of λ is defined to be the dimension of $E_\lambda(A)$.

Def. Since $P_A(\lambda)$ is a polynomial of degree n , we can write $P_A(\lambda) = (\lambda - \lambda_1)^{n_1} (\lambda - \lambda_2)^{n_2} \dots (\lambda - \lambda_k)^{n_k}$ where $\lambda_1, \dots, \lambda_k$ are the distinct roots of $P_A(\lambda)$. The multiplicity of the root λ_i is called the algebraic multiplicity of the eigenvalue λ . So the algebraic multiplicity of $\lambda_i = n_i$. Of course, $n_1 + n_2 + \dots + n_k = n$.

Theorem 3: Let A be any $n \times n$ matrix and $\lambda_1, \lambda_2, \dots, \lambda_n$ be the eigenvalues of A with the multiplicities of the roots taken into consideration. Then (a) $\lambda_1 + \lambda_2 + \dots + \lambda_n = \text{Trace}(A)$, and (b) $\lambda_1 \cdot \lambda_2 \cdot \dots \cdot \lambda_n = \det(A)$.

Proof (a) Since $\lambda_1, \dots, \lambda_n$ are the n eigenvalues of A , (6)

$$p_A(\lambda) = (\lambda - \lambda_1)(\lambda - \lambda_2) \dots (\lambda - \lambda_n) \\ = \lambda^n - (\lambda_1 + \lambda_2 + \dots + \lambda_n)\lambda^{n-1} + \dots + (-1)^n(\lambda_1 \dots \lambda_n)$$

Now let us find $p_A(\lambda)$ by using Laplace's cofactor expansion of $\det(\lambda I - A)$. We have $p_A(\lambda) = \det(\lambda I - A)$

$$= (\lambda - a_{11}) \cdot (-1)^{1+1} \det(M_{11}) + (-a_{12}) \cdot (-1)^{1+2} \det(M_{12}) + \dots + (-a_{1n}) \cdot (-1)^{1+n} \det(M_{1n})$$

$$= (\lambda - a_{11}) \begin{vmatrix} \lambda - a_{22} & -a_{23} & \dots & -a_{2n} \\ -a_{32} & \lambda - a_{33} & \dots & -a_{3n} \\ \vdots & \vdots & \ddots & \vdots \\ -a_{n2} & -a_{n3} & \dots & \lambda - a_{nn} \end{vmatrix} + \underbrace{p_{n-2}(\lambda)}_{\text{polynomial of deg } (n-2) \text{ in } \lambda}$$

$$= (\lambda - a_{11}) \left[\lambda - (a_{22} + \dots + a_{nn})\lambda + p_{n-3}(\lambda) \right] + p_{n-2}(\lambda)$$

$$= \lambda^n - (a_{11} + a_{22} + \dots + a_{nn})\lambda^{n-1} + p_{n-2}(\lambda)$$

So $\lambda_1 + \lambda_2 + \dots + \lambda_n = a_{11} + a_{22} + \dots + a_{nn} = \text{Tr}(A)$.

(b) Also if we put $\lambda = 0$ in the determinant, we get $p_A(0) = \det(0I - A) = \det(-A) = (-1)^n \det(A)$

But $p_A(\lambda) = (0 - \lambda_1)(0 - \lambda_2) \dots (0 - \lambda_n) = (-1)^n (\lambda_1 \dots \lambda_n)$.

So $\lambda_1 \lambda_2 \dots \lambda_n = \det(A)$.

Prop. 4: (a) If A is a symmetric matrix, then all of its eigenvalues are real.

(b) AB & BA have the same set of eigenvalues.

Proof (a) Suppose A is symmetric. Then $A^T = A$. So if λ is an eigenvalue & \underline{x} is a corresponding eigenvector then $A^T \underline{x} = \lambda \underline{x}$ & $A \underline{x} = \lambda \underline{x}$. Now $A \underline{x} \cdot \underline{x} = \underline{x} \cdot (A \underline{x})$
So $(A \underline{x})^T \underline{x} = \underline{x}^T (A \underline{x})$. $\therefore \lambda \underline{x}^T \underline{x} = \underline{x}^T \lambda \underline{x} = \lambda \underline{x}^T \underline{x}$. $\therefore \lambda = \bar{\lambda}$.

(b) Supp. \underline{x} is an eigenvector of AB corresp. to λ . Then $B \underline{x} \neq \underline{0}$ & $(BA)(B \underline{x}) = B(AB) \underline{x} = B \lambda \underline{x} = \lambda (B \underline{x})$. So λ is an eigenvalue of BA . The converse follows similarly.

§3. Diagonalization of matrices & matrix exponentiation (7)

Theorem :: If an $n \times n$ matrix A has n linearly independent eigenvectors, then we can find an invertible matrix P such that $P^{-1}AP = D$ where D is the diagonal matrix consisting of the eigenvalues of A .

Ex.1 Let $A = \begin{bmatrix} 4 & -2 \\ 1 & 1 \end{bmatrix}$. Find a matrix P such that $P^{-1}AP = D$, where D is a diagonal matrix.

Sol. Suppose $\det(\lambda I - A) = 0$. Then $\begin{vmatrix} \lambda - 4 & 2 \\ -1 & \lambda - 1 \end{vmatrix} = 0$
So $(\lambda - 4)(\lambda - 1) - (-2) = 0 \therefore \lambda^2 - 5\lambda + 6 = 0$
 $\therefore (\lambda - 3)(\lambda - 2) = 0 \therefore \lambda_1 = 3 \text{ \& } \lambda_2 = 2$.
So the eigen values are 3 & 2.

For $\lambda_1 = 3$, the system $(\lambda_1 I - A)x = 0$ becomes
 $\begin{bmatrix} 3 - 4 & 2 \\ -1 & 3 - 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, So $-x_1 + 2x_2 = 0$
 $-x_1 + 2x_2 = 0$
 $\therefore x_2 = \alpha$ and $x_1 = 2x_2 = 2\alpha$. So the eigenvectors corresponding to λ_1 are $\alpha \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ with $\alpha \neq 0$.

For $\lambda_2 = 2$, the system $(\lambda_2 I - A)x = 0$ becomes
 $\begin{bmatrix} 2 - 4 & 2 \\ -1 & 2 - 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$. So $-2x_1 + 2x_2 = 0$
 $-x_1 + x_2 = 0$
 $\therefore x_2 = \beta$ and $x_1 = x_2 = \beta$. So the eigenvectors corresponding to λ_2 are $\beta \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ with $\beta \neq 0$.

Any set of 2 independent eigenvectors of A can be taken as the columns of the matrix P .

Ex.1 So choose $P = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$. $P^{-1} = \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$ and (8)

$$\begin{aligned} P^{-1}AP &= \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 4 & -2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 6 & 2 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = D. \end{aligned}$$

Ex.2 Let $A = \begin{bmatrix} 2 & 2 \\ 2 & -1 \end{bmatrix}$. Find an orthogonal matrix P such that $P^{-1}AP = D$ where D is a diagonal matrix.

Sol. Suppose $\det(\lambda I - A) = 0$. Then $\begin{vmatrix} \lambda - 2 & -2 \\ -2 & \lambda + 1 \end{vmatrix} = 0$.

$$\text{So } (\lambda - 2)(\lambda + 1) + 4 = 0 \quad \therefore \lambda^2 - \lambda - 6 = 0.$$

' $(\lambda - 3)(\lambda + 2) = 0$. So $\lambda_1 = 3$ & $\lambda_2 = -2$ are the eigenvalues of A .

For $\lambda_1 = 3$, the system $(\lambda_1 I - A)x = 0$ becomes

$$\begin{bmatrix} 3 & -2 & -2 \\ -2 & 3 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \therefore \begin{aligned} x_1 - 2x_2 &= 0 \\ -2x_1 + 4x_2 &= 0 \end{aligned}$$

$\therefore x_2 = \alpha$ and $x_1 = 2x_2 = 2\alpha$. So the eigenvectors corresponding to λ_1 are $\alpha \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ with $\alpha \neq 0$.

For $\lambda_2 = -2$, the system $(\lambda_2 I - A)x = 0$ becomes

$$\begin{bmatrix} -2 & -2 & -2 \\ -2 & -2 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \therefore \begin{aligned} -4x_1 - 2x_2 &= 0 \\ -2x_1 - x_2 &= 0 \end{aligned}$$

$\therefore x_2 = 2\beta$ $x_1 = -x_2/2 = -\beta$. So the eigenvectors corresponding to λ_2 are $\beta \begin{pmatrix} -1 \\ 2 \end{pmatrix}$ with $\beta \neq 0$.

If we take any two independent unit eigenvectors of A as the columns of P , P will be an orthogonal matrix.

Ex. 2 This is true because A was a symmetric matrix. (9)

$$\text{So take } P = \begin{bmatrix} 2/\sqrt{5} & -1/\sqrt{5} \\ 1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix}. \text{ Then } P^{-1} = P^T = \begin{bmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ -1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix}.$$

$$\begin{aligned} \text{So } P^{-1}AP &= \begin{bmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ -1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix} \begin{bmatrix} 2 & 2 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 2/\sqrt{5} & -1/\sqrt{5} \\ 1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix} \\ &= \begin{bmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ -1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix} \begin{bmatrix} 6/\sqrt{5} & 2/\sqrt{5} \\ 3/\sqrt{5} & -4/\sqrt{5} \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}. \end{aligned}$$

Note: If we take any two independent eigenvectors of A as the columns of a matrix Q , then we will still have $Q^{-1}AQ = D[\lambda_1, \lambda_2]$, but Q would not, in general, be orthogonal. For example, take $Q = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$. Then $Q^{-1} = \frac{1}{5} \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix}$.

$$\begin{aligned} \text{So } Q^{-1}AQ &= \frac{1}{5} \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 2 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \\ &= \frac{1}{5} \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 6 & 2 \\ 3 & -4 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 15 & 0 \\ 0 & -10 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \end{aligned}$$

Ex. 3 Let $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$. Show that A has only one independent eigenvector and hence cannot be diagonalized.

Sol. Supp. $\det(\lambda I - A) = 0$. Then $\begin{vmatrix} \lambda - 1 & -2 \\ 0 & \lambda - 1 \end{vmatrix} = 0$. So $(\lambda - 1)(\lambda - 1) = 0$. $\therefore \lambda = 1$ (twice)

$$\begin{aligned} \text{So } \lambda_1 = 1 \text{ \& } \lambda_2 = 1. \text{ For } \lambda_1 = 1, \text{ we have } \begin{bmatrix} 1-1 & -2 \\ 0 & 1-1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \text{So } \begin{cases} 0x_1 - 2x_2 = 0 \\ 0x_1 - 0x_2 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = \alpha \\ x_2 = 0 \end{cases} \end{aligned}$$

$\therefore \alpha \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ are the only eigenvectors of A when $\alpha \neq 0$.
Since A does not have 2 indep. eigenvectors, A is not diagonalizable.

Ex 4 Let A be the matrix $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$. Diagonalize A . (10)

Sol. $\det(\lambda I - A) = \begin{vmatrix} \lambda - 0 & -1 \\ -1 & \lambda - 0 \end{vmatrix} = \lambda^2 - 1 = 0 \Rightarrow (\lambda - 1)(\lambda + 1) = 0.$

$\therefore \lambda_1 = 1$ and $\lambda_2 = -1$

For $\lambda_1 = 1$, we have $(\lambda_1 I - A)\underline{x} = \underline{0}$, so

$$\begin{bmatrix} 1-0 & -1 \\ -1 & 0-0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

For $\lambda_2 = -1$, we have $(\lambda_2 I - A)\underline{x} = \underline{0}$, so

$$\begin{bmatrix} -1-0 & -1 \\ -1 & -1-0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \underline{0} \Rightarrow \underline{x} = \beta \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$\therefore P = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$, so $P^{-1} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$

$$P^{-1}AP = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 2 & 0 \\ 0 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

So the diagonal matrix that is similar to A

is $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$. Note: $\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$ is also similar to A .

Example 5: Let $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$. Find the eigenvalues of A and one eigenvector for each eigenvalue. Then find the diagonal form that is similar to A . (10)

$$|A - \lambda I| = \begin{vmatrix} 0 - \lambda & -1 \\ 1 & 0 - \lambda \end{vmatrix} = \lambda^2 + 1 \Rightarrow (\lambda - i)(\lambda + i) = 0$$

$\therefore \lambda_1 = i \text{ \& } \lambda_2 = -i$

For $\lambda_1 = i$, we have $(A - \lambda_1 I)\underline{x} = \underline{0}$, so

$$\begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

↓

For $\lambda_2 = -i$ we have $(A - \lambda_2 I)\underline{x} = \underline{0}$, so

$$\begin{bmatrix} i & -1 \\ 1 & i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \beta \begin{bmatrix} 1 \\ i \end{bmatrix}$$

So we can take $\underline{u}_1 = \begin{bmatrix} 1 \\ -i \end{bmatrix}$ & $\underline{u}_2 = \begin{bmatrix} 1 \\ i \end{bmatrix}$

Let $P = [\underline{u}_1, \underline{u}_2] = \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix}$. Then $P^{-1} = \frac{1}{2i} \begin{bmatrix} -i & -1 \\ i & 1 \end{bmatrix}$

So

$$P^{-1}AP = \frac{1}{2i} \begin{bmatrix} -i & -1 \\ i & 1 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix}$$

$$= \frac{1}{2i} \begin{bmatrix} -i & -1 \\ i & 1 \end{bmatrix} \begin{bmatrix} -i & i \\ 1 & 1 \end{bmatrix} = \frac{1}{2i} \begin{bmatrix} -2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$= \frac{1}{2i} \begin{bmatrix} 2i^2 & 0 \\ 0 & -2i^2 \end{bmatrix} = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

The exponential of a matrix.

Def. Recall that $e^x = \sum_{k=0}^{\infty} (x^k/k!)$. Let A be an $n \times n$ matrix. We define e^A by

$$e^A = \sum_{k=0}^{\infty} \left(\frac{1}{k!}\right) \cdot A^k \quad (\text{Here } A^0 = I_n \text{ for any } A.)$$

Fact: If $A = D [d_1, \dots, d_n]$ is a diagonal matrix then $e^A = D [e^{d_1}, \dots, e^{d_n}]$

Proof:

$$\begin{aligned} e^A &= \sum_{k=0}^{\infty} \frac{1}{k!} A^k = \sum_{k=0}^{\infty} \frac{1}{k!} \cdot (D [d_1, \dots, d_n])^k \\ &= \sum_{k=0}^{\infty} \frac{1}{k!} D [d_1^k, \dots, d_n^k] = \\ &= D \left[\sum_{k=0}^{\infty} \frac{1}{k!} d_1^k, \dots, \sum_{k=0}^{\infty} \frac{1}{k!} d_n^k \right] \\ &= D [e^{d_1}, \dots, e^{d_n}] \end{aligned}$$

Ex.: Let $A = \begin{bmatrix} 4 & -2 \\ 1 & 1 \end{bmatrix}$. Find e^A .

Sol. We know that $P^{-1}AP = D$ where $P = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$, $P^{-1} = \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$, and $D = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$. So $A = PDP^{-1}$. Thus

$$A^2 = (PDP^{-1})(PDP^{-1}) = PDP^{-1}PDP^{-1} = PD^2P^{-1}$$

$$\vdots$$
$$A^k = (PDP^{-1})^k = PD^kP^{-1}$$

$$\therefore e^A = \sum_{k=0}^{\infty} \frac{1}{k!} A^k = \sum_{k=0}^{\infty} \frac{1}{k!} (PDP^{-1})^k$$

$$= \sum_{k=0}^{\infty} \frac{1}{k!} PD^kP^{-1} = P \left(\sum_{k=0}^{\infty} \frac{1}{k!} D^k \right) P^{-1} = P(e^D)P^{-1}$$

$$= \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} e^3 & 0 \\ 0 & e^2 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} 2e^3 & e^2 \\ e^3 & e^2 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 2e^3 + e^2 & 2e^2 - 2e^3 \\ e^3 - e^2 & 2e^2 - e^3 \end{bmatrix} = \begin{bmatrix} e^2(2e+1) & 2e^2(1-e) \\ e^2(e-1) & e^2(2-e) \end{bmatrix}$$