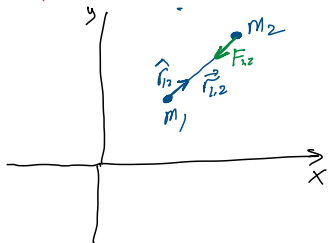


Final Formula for Gravitational Force



$$\vec{F}_{1,2} = -G \frac{m_1 m_2}{r_{1,2}^2} \hat{r}_{1,2} = -\frac{G m_1 m_2 \vec{r}_{1,2}}{r_{1,2}^3}$$

$$\hat{r}_{1,2} = \frac{\vec{r}_{1,2}}{|\vec{r}_{1,2}|}$$

$$\left| \frac{\vec{r}_{1,2}}{|\vec{r}_{1,2}|} \right| = \frac{|\vec{r}_{1,2}|}{|\vec{r}_{1,2}|} = 1$$

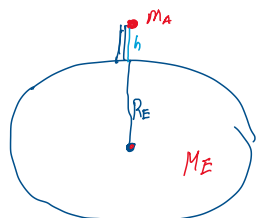
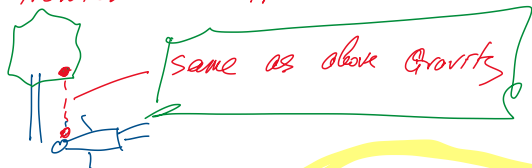
m_1, m_2 — gravitational mass

in principle not same as inertial mass

— Fact $m^G = m^I$!

— $G = 6.67 \times 10^{-11} \frac{m^2}{kg^2}$

⇒ Newton and Apple



$$F_{EA} = G \frac{M_A M_E}{(R_E + h)^2}$$

Newton's Second Law $F = ma$

$$F = M_A g$$

$g = 9.81 \frac{m}{s^2}$

$$G \frac{M_A M_E}{(R_E + h)^2} = M_A g$$

$$g = \frac{G M_E}{(R_E + h)^2}$$

$h = 3m$
 $R_E = 6400000m$

$$g = \frac{G M_E}{R_E^2} = 9.81 \frac{m}{s^2}$$

$$M_E = \frac{g R_E^2}{G}$$

$g_{Moon} = 1.6 \frac{m}{s^2}$

$M_{Moon} = g_{Moon} R_{Moon}^2 / G$

R_{Moon} ——— 1 Moon ——— G

$$g = \frac{GM_E}{(R_E + h)^2}$$

$$h = 0 \quad g = 9.81 \frac{M}{S^2}$$

$$h = 10 \text{ km} \quad g = 9.77 \frac{M}{S^2}$$

$$h = 40 \text{ km} \quad g = 9.67 \frac{M}{S^2}$$

g - what it is

⇒ Gravitational Potential Energy

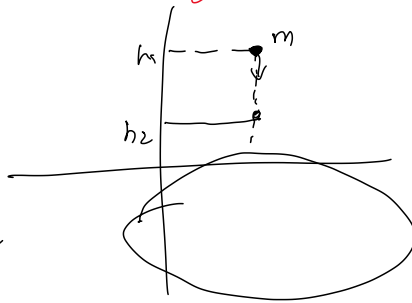
$$W = U_1 - U_2$$

$$W = mgh_1 - mgh_2$$

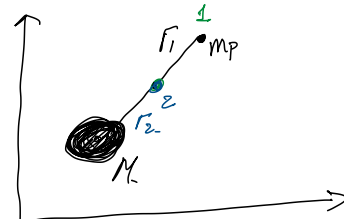
$$W = \underline{F \cdot \Delta y} = \underline{-mg(h_2 - h_1)} = mgh_1 - mgh_2$$

$$U = mgh$$

$$F = mg$$



$$\vec{F} = -\frac{GM_1M_2}{r^2} \hat{r}_{12}$$



$$W = \int_1^2 \vec{F} \cdot d\vec{r} = -\int_{r_1}^{r_2} \frac{GMmp}{r^2} dr$$

$$W = -GMmp \int_{r_1}^{r_2} \frac{dr}{r^2} =$$

$$\left\{ \frac{dr}{r^2} = -\frac{1}{r} \right\}$$

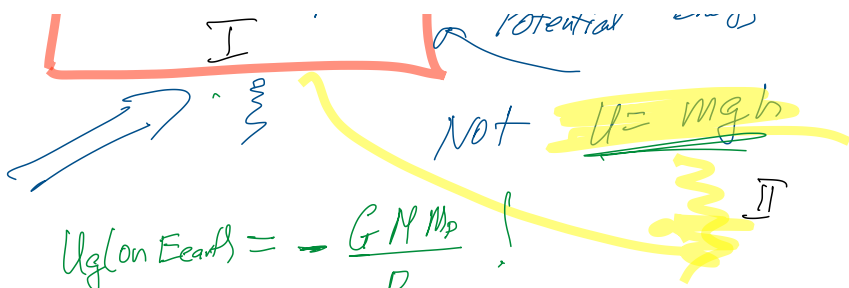
$$= GMmp \frac{1}{r} \Big|_{r_1}^{r_2} = \frac{GMmp}{r_2} - \frac{GMmp}{r_1} = U_1 - U_2$$

$$r_2 = R_E + h_2$$

$$r_1 = R_E + h_1$$

$$U = -\frac{GMmp}{r}$$

True Gravitational
D.I. In France

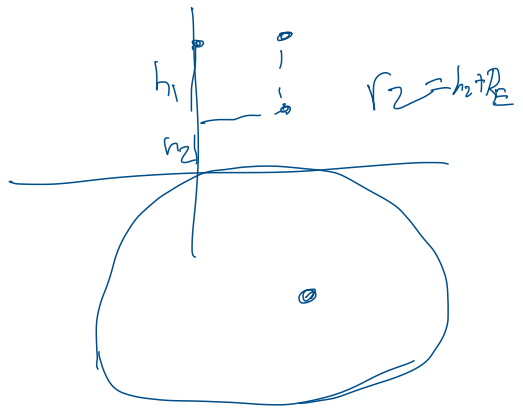


- I $U_{g(\text{on Earth})} = - \frac{GMm_p}{R_E}$!

- II $U(\text{on Earth}) = 0$

$W_g = mgh_1 - mgh_2$

$W_g = \frac{GMm_p}{R_E + h_2} - \frac{GMm_p}{R_E + h_1}$



$\frac{1}{R+h} = \frac{1}{R(1+\frac{h}{R})} \approx \frac{1}{R} \left(1 - \frac{h}{R}\right) = \frac{1}{R} - \frac{h}{R^2}$

$h \ll R$

$W_g = GMm_p \left(\frac{1}{R} - \frac{h_2}{R^2} \right) - GMm_p \left(\frac{1}{R} - \frac{h_1}{R^2} \right)$

$W_g = \cancel{GMm_p \frac{1}{R}} - \frac{GMm_p}{R^2} h_2 - \cancel{\frac{GMm_p}{R}} + \frac{GMm_p}{R^2} h_1$

$W_g = mgh_1 - mgh_2$

$h \ll R_E$

$\rho = \frac{M}{V} \implies \text{in Earth } U = -\frac{GM}{r}$

$$U_g = -\frac{GM}{r}$$

⇒ Escape Velocities

① m_p, V $K_1 = \frac{m_p V^2}{2}$ $E_1 = U + K = -\frac{GMm_p}{R_E} + \frac{1}{2} m_p V^2$

$$E_1 = E_2 \quad \left| \quad -\frac{GMm_p}{R_E} + \frac{1}{2} m_p V^2 = \frac{1}{2} m_p V_f^2 \right.$$

$V_f = 0$

$V_E = ?$

$$-\frac{GMm_p}{R_E} + \frac{1}{2} m_p V_E^2 = 0$$

$$\frac{1}{2} m_p V_E^2 = \frac{GMm_p}{R_E} \quad \left| \quad V_E^2 = \frac{2GM}{R_E} \right.$$

$$V_E = \sqrt{\frac{2GM}{R_E}} \stackrel{E_{\text{cart}}}{=} \sqrt{2gR_E}$$

$$V_E = \sqrt{\frac{2GM}{R_E} \frac{R_E}{R_E}} = \sqrt{2gR_E}$$

g

$$V_E = \sqrt{2gR_E} = \underline{11.2 \frac{km}{s}} = \underline{25000 \frac{mi}{h}}$$

$$9.81 \frac{m}{s^2} \quad 6400000 \text{ m}$$

$$V_E^{Sun} = \sqrt{\frac{2 G M_{Sun}}{R_{Sun}}} = 618 \frac{km}{s} = 1381600 \frac{mi}{h}$$

$$V_E^{Moon} = \sqrt{\frac{2 G M_{Moon}}{R_{Moon}}} = 2.38 \frac{km}{s} = 5320 \frac{mi}{h}$$

Escape Planetary System

$$V_E^{PS} = \sqrt{\frac{2 G (M_{Sun} + M_{Planet})}{R_{PS}}} = 42 \frac{km}{s}$$

⇒ Voyager Missions — 1977 October

⇒ Black Holes

$$V_E = \sqrt{\frac{2GM_s}{R_s}}$$

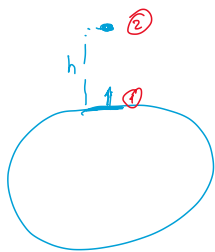
$(M_s, R_s) \nearrow$ $V_E > C = 186000 \frac{mi}{s} \approx 3 \times 10^8 \frac{m}{s}$

⇒ $M_{sun} - R_{sun}$ it to become a B.H

$$V_E = C \Rightarrow C = \sqrt{\frac{2GM_{sun}}{R_{BH}}} \Rightarrow C^2 = \frac{2GM_E}{R_{BH}}$$

$$R_{BH} = \frac{2GM_s}{C^2} \quad R_s = 3cm$$

Example



$$h = 200km$$

$$m = \dots$$

$$V_f = \dots$$

$$U_g = -\frac{GM_E m}{r}$$

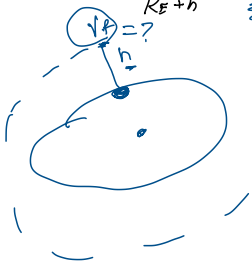
$$E^{(1)} = U_1 + K_1$$

$$E^{(2)} = U_2 + K_2$$

$V_i = ?$

$$E^{(1)} = -\frac{GM_E m_s}{R_E} + \frac{1}{2} m_s V_i^2$$

$$E^{(2)} = -\frac{GM_E m_s}{R_E + h} + \frac{1}{2} m_s V_f^2$$



$$V = \omega \cdot r, \quad V_f = \omega \cdot (R+h)$$

$$-\frac{GM_E m_s}{R_E} + \frac{1}{2} m_s V_i^2 = -\frac{GM_E m_s}{R_E + h} + \frac{1}{2} m_s V_f^2$$

ω_{rot}

$$24h \rightarrow \Delta\phi = 2\pi$$

$$\omega = \frac{\Delta\phi}{\Delta t} = \frac{2\pi}{24 \cdot 60 \cdot 60} = (\omega) \frac{rad}{s}$$

1. Linear Motion $\begin{cases} 1d \\ 2d \end{cases} \begin{cases} Kinematics \\ Dynamics \end{cases}$

2. Rotational Motion $2d \begin{cases} Kinematics \\ Dynamics \end{cases}$

3. Periodic Motion

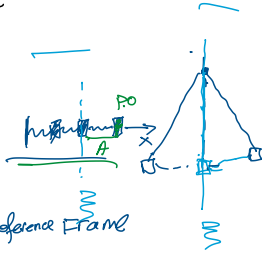
4. Wave Motion

Periodic Motion

- Motion that repeats itself after some time

- **Oscillations**

⇒ Describe Oscillations



Spring

1) Equilibrium Point (E.P.) Reference Frame

2) Position of (P.O.) around E.P., $x(t)$, m , \pm

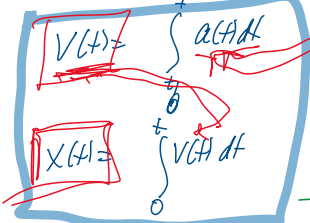
3) Changing the position during the time
↳ Displacement

4) Velocity of P.O. $V(t) = \frac{dx(t)}{dt}$ $\frac{m}{s}$ \pm
Instantaneous Velocity

5) Instantaneous acceleration $a(t) = \frac{dv(t)}{dt}$

Equation of Motion

$a(t) \neq \text{const}$ (Addit Version)



6) Amplitude A , m \pm

7) Period T , s \rightarrow

8) Frequency $\frac{1}{T} = f$, $[f] = \frac{1}{s} = \text{Hertz}$
Heinrich Hertz (1857 - 1894)

9) Angular Frequency

$$\omega = 2\pi f \quad [\omega] = \frac{\text{rad}}{s}$$

⇒ Dynamics

Force \rightarrow Restoring Force

$$F_x = -kx(t)$$



$$2) \quad F_x = m \cdot a_x \quad \Rightarrow \quad F_x(t) = m a_x(t) \quad \Rightarrow \quad -kx(t) = m a_x(t) \quad \Rightarrow \quad a_x(t) = -\frac{k}{m} x(t)$$

$$a_x(t) = \frac{dv(t)}{dt} = \frac{d}{dt} \left(\frac{dx(t)}{dt} \right) = \frac{d^2 x(t)}{dt^2} \quad \text{Second Derivative of } x(t)$$

$$\rightarrow \quad -kx(t) = m \frac{d^2 x(t)}{dt^2} \quad \Rightarrow \quad m \frac{d^2 x(t)}{dt^2} + kx(t) = 0$$

↳ Solution

$$x(t) = A \cos(Bt + C)$$

A, B, C - are constants?

Equation of Simple Harmonic Motion

$$f(t) = \cos(Bt + C)$$

$$\frac{df(t)}{dt} = -B \sin(Bt + C)$$

$$f_0(t) = \sin(Bt + C)$$

$$V(t) = \frac{dx(t)}{dt} = A \frac{d \cos(Bt + C)}{dt} = -AB \sin(Bt + C)$$

$$d^2 x(t) = dV(t) = -AB \frac{d \sin(Bt + C)}{dt} = -AB \cos(Bt + C) \quad \frac{d(A)}{dt} = B \cos(Bt + C)$$

$$\frac{d^2x}{dt^2} = -B^2 A \cos(Bt+C) = -B^2 X(t)$$

$$\frac{d^2 X(t)}{dt^2} = -B^2 X(t)$$

$$-mB^2 X(t) + K X(t) = 0 \quad \left| \quad \frac{mB^2 X(t)}{X(t)} = \frac{K X(t)}{X(t)} \right.$$

$$-mB^2 + K = 0$$

$$mB^2 = K$$

$$B^2 = \frac{K}{m}; \quad B = \sqrt{\frac{K}{m}}$$

$$X(t) = A \cos(Bt + C)$$

$$B = \sqrt{\frac{K}{m}}$$

A = Amplitude

$$X^{\max} = A$$

$$\rightarrow X(0) = A \cos(C)$$

$$\rightarrow X(T) = A \cos(BT + C)$$

$$A \cos C = A \cos(BT + C)$$

$$\cos(C) = \cos(BT + C)$$

$$BT = 2\pi$$

$$\cos(C) = \cos(2\pi + C) = \cos(C)$$

$$BT = 2\pi$$

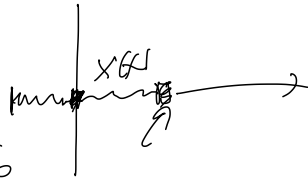
$$B = \frac{2\pi f}{T} = 2\pi \cdot f = \omega$$

$$\cos(2\pi + \theta) = \cos \theta$$

$$v(t) = A \cos(\omega t + C)$$

$$\omega = B = \sqrt{\frac{K}{m}}$$

$$x(t) = A \cos(\omega t)$$



ω - defines $x(0) = x_0$

phase $\rightarrow \varphi$

$2\pi f$

$$\omega = \sqrt{\frac{k}{m}}$$

A - amplitude

φ - phase

$$x(t) = A \cos(\omega t + \varphi)$$

$$v(t) = \frac{dx(t)}{dt} = \frac{dA \cos(\omega t + \varphi)}{dt} = -\omega A \sin(\omega t + \varphi)$$

$$v(t) = -\omega A \sin(\omega t + \varphi) \quad \leftarrow \text{Equation of Motion}$$

$$x_i = A \cos \varphi$$

$$v_i = -\omega A \sin \varphi$$

$$\frac{v_i}{x_i} = \frac{-\omega A \sin \varphi}{A \cos \varphi} = -\omega \tan \varphi$$

$$\varphi = \tan^{-1}\left(\frac{-v_i}{\omega x_i}\right)$$

$$\begin{cases} x_i^2 = (A \cos \varphi)^2 \\ \left(-\frac{v_i}{\omega}\right)^2 = (A \sin \varphi)^2 \end{cases}$$

$$x_i^2 = A^2 \cos^2 \varphi$$

$$+ \frac{v_i^2}{\omega^2} = A^2 \sin^2 \varphi$$

$$x_i^2 + \frac{v_i^2}{\omega^2} = A^2 \cos^2 \varphi + A^2 \sin^2 \varphi = A^2 (\cos^2 \varphi + \sin^2 \varphi) = A^2 \cdot 1$$

$$A^2 = x_i^2 + \frac{v_i^2}{\omega^2}$$

$$A = \sqrt{x_i^2 + \frac{v_i^2}{\omega^2}}$$

