

$$R(\hat{n}, \theta) \equiv D_{\frac{1}{2}}(\hat{n}, \theta) = I \cos\left(\frac{\theta}{2}\right) - i(\hat{G} \cdot \hat{n}) \sin\frac{\theta}{2}$$

where $\hat{G} \cdot \hat{n} = \sigma_x n_x + \sigma_y n_y + \sigma_z n_z$

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

- If we would like to rotate the reference frame then $\theta = -\theta$

- Consider that originally we measured the quantum state of spin $\frac{1}{2}$ particle in z direction

- Before the measurement

$$|r\rangle = \alpha |↑\rangle + \beta |↓\rangle$$

- α, β probability amplitude that out come of measurement is along \hat{z}

- Naturally $\alpha^2 + \beta^2 = 1$ opposite to \hat{z}

① Suppose the measurement resulted in along \hat{z} state

② Thus state will collapse to $|↑\rangle$ state

③ Now you want to measure this collapsed state in arbitrary \hat{n} direction

You take this original basis states and rotate \hat{z} along \hat{y} axis



$$D(y, \theta) = R(y, \theta) = I \cos\frac{\theta}{2} + i \sigma_y \frac{\sin\frac{\theta}{2}}{2} = \begin{pmatrix} \cos\frac{\theta}{2} & \sin\frac{\theta}{2} \\ -\sin\frac{\theta}{2} & \cos\frac{\theta}{2} \end{pmatrix}$$

$$= \begin{pmatrix} \cos\frac{\theta}{2} & \sin\frac{\theta}{2} \\ -\sin\frac{\theta}{2} & \cos\frac{\theta}{2} \end{pmatrix}$$

$$D(\hat{y}, -\theta)(\uparrow) = \begin{pmatrix} \cos\theta/2 & \sin\theta/2 \\ -\sin\theta/2 & \cos\theta/2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos\theta/2 \\ -\sin\theta/2 \end{pmatrix} \equiv |\vec{\uparrow}_\theta\rangle$$

$$D(\hat{y}, -\theta)(\downarrow) = \begin{pmatrix} \cos\theta/2 & \sin\theta/2 \\ -\sin\theta/2 & \cos\theta/2 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \sin\theta/2 \\ \cos\theta/2 \end{pmatrix} \equiv |\vec{\downarrow}_\theta\rangle$$

Thus new orthonormal basis is $(|\vec{\uparrow}_\theta\rangle, |\vec{\downarrow}_\theta\rangle)$

4) Calculate probability that collapsed state $|\uparrow\rangle$ will be measured along $|\vec{\uparrow}_\theta\rangle$ and $|\vec{\downarrow}_\theta\rangle$

$$\begin{pmatrix} \langle \vec{\uparrow}_\theta | \\ \langle \vec{\downarrow}_\theta | \end{pmatrix} |\uparrow\rangle = \begin{pmatrix} \langle \vec{\uparrow}_\theta | \uparrow \rangle \\ \langle \vec{\downarrow}_\theta | \uparrow \rangle \end{pmatrix}$$

$$\langle \vec{\uparrow}_\theta | \uparrow \rangle = (\cos\theta/2, -\sin\theta/2) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos\theta/2 \\ 0 \end{pmatrix}$$

$$\langle \vec{\downarrow}_\theta | \uparrow \rangle = (\sin\theta/2, \cos\theta/2) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \sin\theta/2 \\ 0 \end{pmatrix}$$

Algebra for Spin

⇒ General Property of Rotation

⇒ Rotating Spin states

$$T = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} |1\rangle \\ |0\rangle \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} + \frac{i}{\sqrt{2}} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$

$$(1 \uparrow, 1 \downarrow) \quad |1 \uparrow\rangle = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad |1 \downarrow\rangle = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$(1 \rightarrow 1 \leftarrow) \quad 1 \rightarrow = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \quad 1 \leftarrow = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$A^\dagger = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$A^\dagger |1 \uparrow\rangle = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

Measuring in vertical direction

$$|1 \uparrow\rangle = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{\sqrt{2}} |1 \uparrow\rangle - \frac{1}{\sqrt{2}} |1 \downarrow\rangle$$

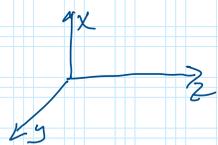
$$|1 \leftarrow\rangle = \frac{1}{\sqrt{2}} |1 \uparrow\rangle + \frac{1}{\sqrt{2}} |1 \downarrow\rangle$$

= Equivalent States

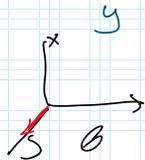
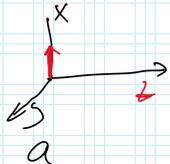
⇒ Rotating Apparatus in 60°

$$\begin{pmatrix} \frac{\sqrt{3}}{2} & 1 \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix} \begin{pmatrix} |1 \uparrow\rangle \\ |1 \downarrow\rangle \end{pmatrix}$$

⇒ Consider Photon Polarization



two polarization
direction x and
y



⇒ Quantum state of (a) $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $\approx \begin{pmatrix} x \\ y \end{pmatrix}$

Quantum state (b) $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$

We can drop z

$$\begin{pmatrix} 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \end{pmatrix}$$

⇒ Rotation in this case is defined
by Rotation of a vector with unit
x and y components

- in our case it is a rotation
around z-axis

$$- R_z(\theta) = \begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$R_z(\theta) |x\rangle = |x'\rangle$$

- If we are rotating the reference
Frame

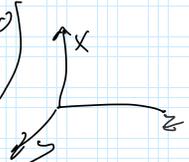
$$R_z(-\theta) = \begin{pmatrix} \cos\theta & +\sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$R_z(-\theta) \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos\theta \\ -\sin\theta \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 \\ 0 & -i \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ -i \end{pmatrix}$$

$$R_z(-\theta) \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos\theta \\ \sin\theta \\ 0 \end{pmatrix}$$

⇒ Suppose initially you have a photon
 stat in $|x\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ $|y\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$



① $|x\rangle = \alpha |x\rangle + \beta |y\rangle$

② You measured and it came up in \hat{x}
 collapsed to $|x_0\rangle$

3) You now measure in \hat{y} and $-\hat{x}$ direction
 $\theta = 30^\circ$

New basis B

$$|\hat{y}_{30}\rangle = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix} \quad |x\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Let what is the probability to measure in
 \hat{y} - direction $|\hat{y}_{30}\rangle$ and in $|x\rangle$
 direction.

$$|x_0\rangle = \beta_1 |y_{20}\rangle + \beta_2 |x\rangle$$

$$A = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \beta_1 \\ \beta_2 \\ 0 \end{pmatrix}$$

$$\beta_1 = 0 \quad \beta_2 = 1$$

\Rightarrow Do the same if $\theta = 45^\circ$

\Rightarrow Then again rotate to $\theta = 45^\circ$

