

HW-5

$$\text{In}[1] = \mathbf{V} = \frac{q}{4 \pi \epsilon_0} \left(\frac{1}{\sqrt{\rho^2 + (z+d)^2}} - \frac{1}{\sqrt{\rho^2 + \left(z + \frac{d}{2}\right)^2}} + \frac{2}{\sqrt{\rho^2 + (z-d)^2}} - \frac{2}{\sqrt{\rho^2 + \left(z - \frac{d}{2}\right)^2}} \right);$$

$$\text{In}[3] = \mathbf{Efield} = \text{FullSimplify} \left[-\mathbf{e}_\rho D[\mathbf{V}, \rho] - \frac{\mathbf{e}_\phi}{\rho} D[\mathbf{V}, \phi] - \mathbf{e}_z D[\mathbf{V}, z] \right]$$

$$\text{Out}[3] = - \frac{q \left(\frac{2(d-z)}{((d-z)^2 + \rho^2)^{3/2}} - \frac{d+z}{((d+z)^2 + \rho^2)^{3/2}} - \frac{8(d-2z)}{((d-2z)^2 + 4\rho^2)^{3/2}} + \frac{4(d+2z)}{((d+2z)^2 + 4\rho^2)^{3/2}} \right) \mathbf{e}_z}{4 \pi \epsilon_0} -$$

$$\frac{q \left(-\frac{2\rho}{((d-z)^2 + \rho^2)^{3/2}} + \frac{2\rho}{\left(-\frac{d}{2}+z\right)^2 + \rho^2}^{3/2} + \frac{\rho}{\left(\frac{d}{2}+z\right)^2 + \rho^2}^{3/2} - \frac{\rho}{((d+z)^2 + \rho^2)^{3/2}} \right) \mathbf{e}_\rho}{4 \pi \epsilon_0}$$

$$\text{In}[5] = \mathbf{E\rho} = \mathbf{Efield} /. z \rightarrow 0 /. \mathbf{e}_0 \rightarrow \mathbf{e}_z$$

$$\text{Out}[5] = - \frac{q \left(\frac{d}{(d^2 + \rho^2)^{3/2}} - \frac{4d}{(d^2 + 4\rho^2)^{3/2}} \right) \mathbf{e}_z}{4 \pi \epsilon_0} - \frac{q \left(\frac{3\rho}{\left(\frac{d^2}{4} + \rho^2\right)^{3/2}} - \frac{3\rho}{(d^2 + \rho^2)^{3/2}} \right) \mathbf{e}_\rho}{4 \pi \epsilon_0}$$

$$\text{In}[6] = \text{Series}[\mathbf{E\rho}, \{d, 0, 2\}]$$

$$\text{Out}[6] = - \frac{(q \sqrt{\rho^2} \mathbf{e}_z) d}{8 (\pi \rho^4 \epsilon_0)} - \frac{27 (q \sqrt{\rho^2} \mathbf{e}_\rho) d^2}{32 (\pi \rho^5 \epsilon_0)} + O[d]^3$$

at $z=0$: dipole $\vec{E} = \frac{-8d}{8\pi\epsilon_0} \frac{1}{\rho^3} \hat{e}_z$

quadrupole $\vec{E} = - \frac{278d^2}{32\pi\epsilon_0} \frac{1}{\rho^4} \hat{e}_\rho$

In[1]= $f = r^2 \cos[\theta] \sin[\phi];$

In[3]= $\text{fcart} = \text{Simplify}[f /. \phi \rightarrow \text{ArcTan}[y/x] /. \theta \rightarrow \text{ArcCos}[\frac{z}{r}] /. r \rightarrow \sqrt{x^2 + y^2 + z^2}]$

Out[3]=
$$\frac{y z \sqrt{x^2 + y^2 + z^2}}{x \sqrt{1 + \frac{y^2}{x^2}}}$$

In[18]= $\text{fgrad} = \{D[\text{fcart}, x], D[\text{fcart}, y], D[\text{fcart}, z]\};$

In[5]= $\text{gradsph} = \text{FullSimplify}[\text{fgrad} /. x \rightarrow r \sin[\theta] \cos[\phi] /. y \rightarrow r \sin[\theta] \sin[\phi] /. z \rightarrow r \cos[\theta]]$

Out[5]=
$$\left\{ -\frac{\sqrt{r^2} \cos[\theta]^2 \cot[\theta] \sin[\phi]}{\sqrt{\sec[\phi]^2}}, \right. \\ \left. \frac{\sqrt{r^2} \cos[\theta] \cos[\phi] \sqrt{\sec[\phi]^2} (\cos[\theta] \cos[\phi]^2 \cot[\theta] + \sin[\theta])}{2 \sqrt{\sec[\phi]^2}}, \right. \\ \left. \frac{\sqrt{r^2} (3 + \cos[2\theta]) \tan[\phi]}{2 \sqrt{\sec[\phi]^2}} \right\}$$

In[6]= $\mathbf{e_r} = \{\sin[\theta] \cos[\phi], \sin[\theta] \sin[\phi], \cos[\theta]\};$
 $\mathbf{e_\theta} = \{\cos[\theta] \cos[\phi], \cos[\theta] \sin[\phi], -\sin[\theta]\};$
 $\mathbf{e_\phi} = \{-\sin[\phi], \cos[\phi], 0\};$

In[12]= $\text{gradr} = \text{FullSimplify}[\text{Dot}[\text{gradsph}, \mathbf{e_r}]]$
 $D[f, r]$

Out[12]=
$$\frac{2 \sqrt{r^2} \cos[\theta] \tan[\phi]}{\sqrt{\sec[\phi]^2}} = 2 r \cos \theta \sin \phi$$

Out[13]= $2 r \cos[\theta] \sin[\phi]$

In[14]= $\text{grad}\theta = \text{FullSimplify}[\text{Dot}[\text{gradsph}, \mathbf{e_\theta}]]$
 $\frac{1}{r} D[f, \theta]$

Out[14]=
$$-\frac{\sqrt{r^2} \sin[\theta] \tan[\phi]}{\sqrt{\sec[\phi]^2}} = -r \sin \theta \sin \phi$$

Out[15]= $-r \sin[\theta] \sin[\phi]$

In[16]= $\text{grad}\phi = \text{FullSimplify}[\text{Dot}[\text{gradsph}, \mathbf{e_\phi}]]$
 $\frac{1}{r \sin[\theta]} D[f, \phi]$

Out[16]=
$$\frac{\sqrt{r^2} \cot[\theta]}{\sqrt{\sec[\phi]^2}} = r \cot \theta \cos \phi$$

Out[17]= $r \cos[\phi] \cot[\theta]$

EMM HW - 5

2-5 when $\vec{r}'$ fixed $\vec{r}$ rotating

$$\ddot{\vec{r}}' = \ddot{\vec{r}} + \vec{\omega} \times \vec{r} + 2\vec{\omega} \times \dot{\vec{r}} + \vec{\omega} \times (\vec{\omega} \times \vec{r})$$

on earth $\ddot{\vec{r}}' = \vec{g}$ $\dot{\vec{\omega}} = 0$ $\vec{\omega}$ small.

so $\ddot{\vec{r}} = \vec{g} - 2(\vec{\omega} \times \dot{\vec{r}}) \Rightarrow$ Coriolis acceleration

up to $\vec{\omega}$ $\mathcal{O}(\omega)$

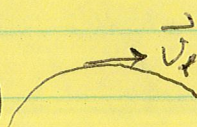
$$\dot{\vec{r}} = \int \ddot{\vec{r}} dt = \vec{v} + \vec{g}t + \mathcal{O}(\omega)$$

so up to $\mathcal{O}(\omega)$

$$\ddot{\vec{r}} = \vec{g} - 2(\vec{\omega} \times (\vec{v} + \vec{g}t)) = \vec{g} - 2(\vec{\omega} \times \vec{v}) - 2(\vec{\omega} \times \vec{g})t$$

$$\dot{\vec{r}} = \vec{v} + \vec{g}t - 2(\vec{\omega} \times \vec{v})t - (\vec{\omega} \times \vec{g})t^2$$

$$\vec{r} = \vec{v}t + \frac{1}{2}\vec{g}t^2 - (\vec{\omega} \times \vec{v})t^2 - \frac{1}{3}(\vec{\omega} \times \vec{g})t^3$$

flight time $\tau = 2 * (\text{time when } \vec{v}_x \cdot \vec{g} = 0)$ 

$$\vec{g} \cdot \dot{\vec{r}} = 0 = \vec{v} \cdot \vec{g} + g^2 t - 2(\vec{\omega} \times \vec{v}) \cdot \vec{g} t - (\vec{\omega} \times \vec{g}) \cdot \vec{g} t^2$$

$$(\vec{\omega} \times \vec{g}) \cdot \vec{g} = (\vec{g} \times \vec{g}) \cdot \vec{\omega} = 0$$

$$(\vec{\omega} \times \vec{v}) \cdot \vec{g} = (\vec{g} \times \vec{\omega}) \cdot \vec{v}$$

$$\text{so } \tau = -2 \frac{\vec{v} \cdot \vec{g}}{g^2} \frac{1}{1 - 2(\vec{g} \times \vec{\omega}) \cdot \vec{v}/g^2}$$

$$\tau = \tau_0 (1 + 2(\vec{g} \times \vec{\omega}) \cdot \vec{v}/g^2) + \mathcal{O}(\omega^2)$$

$$\tau = \tau_0 (1 + \delta) \quad \delta \sim \mathcal{O}(\omega)$$

notice: $\vec{r}(\vec{\omega}=0) = \vec{v}\tau_0 + \frac{1}{2}\vec{g}\tau_0^2$

so $\vec{r} = \vec{r}(\omega=0) + \vec{v}\tau_0\delta + \frac{1}{2}\vec{g}2\tau_0^2\delta + \frac{1}{2}\vec{g}\tau_0^2\delta^2$
 $- (\vec{\omega} \times \vec{v})\tau_0^2(1+\delta)^2 - \frac{1}{3}(\vec{\omega} \times \vec{g})\tau_0^3(1+\delta)^3$

so up to $\mathcal{O}(\omega)$ only δ term remains

$\vec{r} - \vec{r}(\omega=0) = \tau_0(\vec{v} + \vec{g}\tau_0)\delta - (\vec{\omega} \times \vec{v})\tau_0^2 - \frac{1}{3}(\vec{\omega} \times \vec{g})\tau_0^3$

where $\tau_0 = -2 \frac{\vec{v} \cdot \vec{g}}{g^2}$

$\vec{r} - \vec{r}(\omega=0) = \frac{2\tau_0}{g^2} [(\vec{g} \times \vec{\omega}) \cdot \vec{v}](\vec{g}\tau_0 + \vec{v}) - (\vec{\omega} \times \vec{v})\tau_0^2$
 $- \frac{1}{3}(\vec{\omega} \times \vec{g})\tau_0^3 \quad !!$

for $\vec{v} \parallel \vec{\omega}$ $v \sim 300 \text{ m/s}$ $\tau_0 \sim 2 \frac{1}{\sqrt{2}} 300 / 9.8 \sim 43 \text{ s}$

so range $\sim v \frac{1}{\sqrt{2}} * \tau_0 \sim 9000 \text{ m} \sim 9 \text{ km}$

$\vec{r} - \vec{r}(\omega=0) \sim 15 \text{ m!}$ for $\omega = 7.3 \times 10^{-5} \text{ rad/s}$

or: $\vec{g} \cdot \vec{r}(\text{landing}) = 0$,

so, $\vec{g} \cdot \vec{r} = \vec{v} \cdot \vec{g}t + \frac{1}{2}g^2t^2 - (\vec{\omega} \times \vec{v}) \cdot \vec{g}t^2 - \frac{1}{3}(\vec{\omega} \times \vec{g}) \cdot \vec{g}t^3$

$0 = \vec{v} \cdot \vec{g} + \frac{1}{2}g^2t + [(\vec{\omega} \times \vec{v}) \cdot \vec{g}]t \quad !!$

2.10

$$\begin{aligned} \text{a) } \vec{\nabla} \times \vec{a} (\vec{\nabla} \cdot \vec{a}) + \vec{a} \times [\vec{\nabla} \times (\vec{\nabla} \times \vec{a})] + \vec{a} \times \nabla^2 \vec{a} \\ = (\vec{\nabla} \cdot \vec{a}) (\vec{\nabla} \times \vec{a}) - \vec{a} \times \nabla (\vec{\nabla} \cdot \vec{a}) \\ + \vec{a} \times [\vec{\nabla} (\vec{\nabla} \cdot \vec{a}) - \nabla^2 \vec{a}] + \vec{a} \times \nabla^2 \vec{a} \\ = (\vec{\nabla} \cdot \vec{a}) (\vec{\nabla} \times \vec{a}) \end{aligned}$$

$$\begin{aligned} \text{b) } (\vec{\nabla} \times \vec{a}) \cdot (\vec{b} \times \vec{c}) \\ = ((\vec{b} \times \vec{c}) \times \vec{\nabla}) \cdot \vec{a} \\ = [\vec{c} (\vec{b} \cdot \vec{\nabla}) - \vec{b} (\vec{c} \cdot \vec{\nabla})] \cdot \vec{a} \end{aligned}$$

$$\begin{aligned} \text{c) } \vec{a} \times (\vec{\nabla} \times \vec{a}) &= \vec{a} \cdot \vec{\nabla} \vec{a} - (\vec{a} \cdot \vec{\nabla}) \vec{a} \\ &= \vec{\nabla} \left(\frac{1}{2} a^2 \right) - (\vec{a} \cdot \vec{\nabla}) \vec{a} \end{aligned}$$

2-14 cylindrical $\hat{e}_\rho = \{\cos\phi, \sin\phi, 0\}$ in cartesian
 $\hat{e}_\phi = \{-\sin\phi, \cos\phi, 0\}$

clearly $\frac{\partial}{\partial\phi} \hat{e}_\rho = \hat{e}_\phi$ $\frac{\partial}{\partial\phi} \hat{e}_\phi = -\hat{e}_\rho$

i) $\nabla^2 \vec{a}$ $\vec{a} = \hat{e}_\rho$
 $\vec{\nabla} \cdot (\vec{\nabla} \hat{e}_\rho) = \vec{\nabla} \cdot \left(\hat{e}_\rho \frac{\partial}{\partial\rho} \hat{e}_\rho + \hat{e}_\phi \frac{1}{\rho} \frac{\partial}{\partial\phi} (\hat{e}_\rho) + \hat{e}_z \frac{\partial}{\partial z} (\hat{e}_\rho) \right)$
 $= (\vec{\nabla} \cdot) (0 + \hat{e}_\phi \frac{1}{\rho} (\hat{e}_\phi) + 0)$
 $= \frac{1}{\rho} \frac{\partial}{\partial\phi} \left(\frac{1}{\rho} \hat{e}_\phi \right) = -\frac{1}{\rho^2} \hat{e}_\rho$ ✓

ii) $\vec{\nabla} \times \hat{e}_\rho = \frac{1}{\rho} \begin{vmatrix} \hat{e}_\rho & \rho \hat{e}_\phi & \hat{e}_z \\ \frac{\partial}{\partial\rho} & \frac{\partial}{\partial\phi} & \frac{\partial}{\partial z} \\ 1 & 0 & 0 \end{vmatrix} = 0$

$\vec{\nabla} \times (\vec{\nabla} \times \vec{a}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{a}) - \nabla^2 \vec{a} = 0$ $\vec{a} = \hat{e}_\rho$
 so $\nabla (\vec{\nabla} \cdot \vec{a}) = \nabla^2 \vec{a}$

iii) $\vec{\nabla} \cdot \hat{e}_\rho = \frac{1}{\rho} \frac{\partial}{\partial\rho} (\rho \cdot 1) = \frac{1}{\rho}$
 $\nabla (\vec{\nabla} \cdot \hat{e}_\rho) = \nabla \frac{1}{\rho} = \hat{e}_\rho \frac{\partial}{\partial\rho} \left(\frac{1}{\rho} \right) + 0 + 0$
 $\nabla (\vec{\nabla} \cdot \hat{e}_\rho) = -\frac{1}{\rho^2} \hat{e}_\rho$
 $[\nabla (\vec{\nabla} \cdot \hat{e}_\rho)] \cdot \hat{e}_\rho = -\frac{1}{\rho^2}$

clearly $\nabla^2 (\hat{e}_\rho \cdot \hat{e}_\rho) = 0$

so $[\nabla (\vec{\nabla} \cdot \vec{a})]_\rho \neq \nabla^2 a_\rho = \nabla^2 (\vec{a} \cdot \hat{e}_\rho)$

2-14 (b)

$$\begin{aligned}\nabla^2 \hat{e}_\rho &= \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \left(\frac{x}{\sqrt{x^2+y^2}} \hat{e}_x + \frac{y}{\sqrt{x^2+y^2}} \hat{e}_y + 0 \right) \\&= \left[\frac{\partial^2}{\partial x^2} \left(\frac{x}{\sqrt{x^2+y^2}} \right) + \frac{\partial^2}{\partial y^2} \left(\frac{x}{\sqrt{x^2+y^2}} \right) \right] \hat{e}_x \\&\quad \left[\frac{\partial^2}{\partial x^2} \left(\frac{y}{\sqrt{x^2+y^2}} \right) + \frac{\partial^2}{\partial y^2} \left(\frac{y}{\sqrt{x^2+y^2}} \right) \right] \hat{e}_y\end{aligned}$$

$$\begin{aligned}\frac{\partial^2}{\partial x^2} \left(\frac{x}{(x^2+y^2)^{1/2}} \right) &= \frac{\partial}{\partial x} \left[\frac{1}{(x^2+y^2)^{1/2}} - \frac{x^2}{(x^2+y^2)^{3/2}} \right] \\&= \frac{\partial}{\partial x} \frac{y^2}{(x^2+y^2)^{3/2}} = -3 \frac{xy^2}{(x^2+y^2)^{5/2}}\end{aligned}$$

$$\frac{\partial^2}{\partial y^2} \left(\frac{x}{\sqrt{x^2+y^2}} \right) = \frac{\partial}{\partial y} \left(-\frac{xy}{(x^2+y^2)^{3/2}} \right) = -\frac{x}{(x^2+y^2)^{3/2}} + 3 \frac{xy^2}{(x^2+y^2)^{5/2}}$$

$$\text{so } \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{x}{\sqrt{x^2+y^2}} \right) = -\frac{x}{(x^2+y^2)^{3/2}}$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{y}{\sqrt{x^2+y^2}} \right) = -\frac{y}{(x^2+y^2)^{3/2}}$$

$$\nabla^2 \hat{e}_\rho = -\frac{x}{(x^2+y^2)^{3/2}} \hat{e}_x - \frac{y}{(x^2+y^2)^{3/2}} \hat{e}_y = -\frac{1}{\rho^2} \hat{e}_\rho$$

$$2.15 \quad \text{i) } \vec{\nabla} \cdot \vec{B} = 0 \quad \text{ii) } \vec{\nabla} \cdot \vec{E} = 0$$

$$\text{iii) } \vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0 \quad \text{iv) } \vec{\nabla} \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = 0$$

$$\text{let } \vec{B} = \vec{\nabla} \times \vec{A} \quad \vec{E} = -\vec{\nabla} \phi - \frac{\partial \vec{A}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{B} = \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0 \quad \checkmark$$

$$\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = -\vec{\nabla} \times \vec{\nabla} \phi - \frac{\partial}{\partial t} \vec{\nabla} \times \vec{A} + \frac{\partial}{\partial t} \vec{\nabla} \times \vec{A} = 0 \quad \checkmark$$

$$\vec{\nabla} \times \vec{\nabla} \phi = 0$$

$$\text{ii) } \vec{\nabla} \cdot \vec{E} = \nabla^2 \phi + \frac{\partial}{\partial t} \vec{\nabla} \cdot \vec{A} = 0$$

$$\text{if } \vec{\nabla} \cdot \vec{A} + \frac{1}{c^2} \frac{\partial^2 \phi}{\partial t^2} = 0$$

$$\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{A}) + \frac{1}{c^2} \frac{\partial^2 \phi}{\partial t^2} = 0$$

$$\boxed{\nabla^2 \phi - \frac{1}{c^2} \frac{\partial^2 \phi}{\partial t^2} = 0}$$

$$\text{iv) } \vec{\nabla} \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) + \frac{1}{c^2} \frac{\partial}{\partial t} \vec{\nabla} \phi + \frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} = 0$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A}$$

$$\text{if } \vec{\nabla} \cdot \vec{A} + \frac{1}{c^2} \frac{\partial^2 \phi}{\partial t^2} = 0 \quad \nabla (\vec{\nabla} \cdot \vec{A}) + \frac{1}{c^2} \frac{\partial}{\partial t} \vec{\nabla} \phi = 0$$

$$\nabla (\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A} + \frac{1}{c^2} \frac{\partial}{\partial t} \vec{\nabla} \phi + \frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} = 0$$

$$\boxed{\nabla^2 \vec{A} - \frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} = 0}$$